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1 Introduction

The QED 95 is a DEC Unibus-compatible processor that is fully compatible with PDP-11 Unibus hardware and software. The QED 95 addresses four megabytes of memory and implements the complete PDP-11 architecture, excluding the Commercial Instruction Set, (CIS, found only as an option on the 11/23, 11/24, and 11/44 systems). The QED 95 consists of two processor boards, a memory board, and optional host adapter boards. The QED 95 system is designed to replace your current PDP-11 processor and memory.

The QED 95 is manufactured under license from Digital Equipment Corporation. A separate software sublicense available through Quickware is required for each QED processor running a Digital operating system.
2 Features

- High-speed CMOS processor
- 32 KB cache memory
- Floating point implemented in hardware
- Private memory bus (QMI bus)
- Boot ROMs
- Configuration menu
- On-board serial line units
- On-board clock
- Unibus interface
- Massbus interface (when used with 11/70)
- Four megabyte error-correcting memory
- Unibus map
- Concurrent MMU, ALU and DMA operation

2.1 QED 95 CPU

2.1.1 CMOS Processor
The CPU has a major cycle time of 110 nanoseconds (ns), allowing the execution of up to nine million instructions (MIPS) per second. In a typical program, you can expect an average of four MIPS. By comparison, the PDP-11/70 runs at 1.36 MIPS average while the 11/84 runs at 1.56 MIPS. Actual system performance will depend
on the number of users and the amount of I/O activity. The QED 95 memory system allows transfers at over five MB/sec.

2.1.2 Cache Memory

The QED 95 has 32 KB of cache memory. This cache memory allows data and instruction fetches to occur in as little as 110 ns. The 32 KB cache is four times larger than other PDP-11 cache memories and provides a hit rate of over 95 percent.

Parity checking on both cache data and tags helps ensure accurate program execution. If a parity error occurs, the QED 95 will either signal the operating system with a trap or simply ignore the data stored in the cache and refetch the data from main memory. Due to this redundancy, most operating systems will disable the cache parity interrupts by setting the appropriate bit in the Cache Control Register (CCR).

When a Direct Memory Access (DMA) device writes to memory, the CPU checks to see if the address being written is in the cache. If it is, the CPU simply invalidates the cache location. The next time the program requests the data at that location, the CPU will recognize that it is not in the cache and request the data from the memory.

Control bits in the Memory Management Unit (MMU), the CCR and a CPU register allow the cache to be disabled completely, bypassed on data reads only, or bypassed selectively by virtual page address. The CPU never caches the Unibus addresses located in the upper 8 KB of address space.

2.1.3 Floating Point

Floating Point instructions, which are optional on most PDP-11 models, are present in the QED 95 for maximum compatibility with existing software. For high performance, the AMD 29C327 floating-point chip is used, assisted by microcode. This part includes a full FP register set and supports F and D data formats. FIS-11 floating point opcodes are presently not recognized by the QED 95 (these exist only on the 11/03 and 11/40).

2.1.4 QMI Bus

The Quickware Memory Interconnect (QMI) is a proprietary bus that connects the QED 95-CPU and the MS95 memory. This bus allows transfers between the CPU and memory at over five MB per second. Support for disk and tape controllers is provided for future expansion.
2.1.5 Boot ROMs

The QED 95 CPU has two boot ROMs that are mapped into the Unibus address space. Each ROM occupies 256 words of Unibus space. The ROMs are paged via the Boot Page Control Register. The CPU supports up to 64 KB ROMs through this mapping process. In addition, one of the ROMs may be an Electrically Erasable ROM, which allows configuration data to be changed and updated while the board is installed.

The standard configuration is a 32 KB EPROM at location 173000 and an 8 KB EEROM at 165000. Since these addresses are the same as those used by standard Digital bootstrap boards, you can independently disable the ROMs by setting appropriate bits in the Boot and Diagnostic Status Register.

2.1.6 Configuration Menu

In order to eliminate confusion over switch settings, Quickware has provided a configuration menu that enables you to configure the system from the console terminal. Configuration options include boot device selection and on-board device setup.

Some configuration takes place automatically. For instance, if the system has a DL11 terminal interface installed for the console terminal, the boot ROMs and menu automatically disable the on-board SLU.

2.2 MS95 Memory Board

2.2.1 On-board Serial Line Units

There are two DL11-compatible Serial Line Units (SLUs) on the MS95 memory board. They have CSRs located at 17756X and 17650X and vectors at 60 & 300. You can disable the SLUs by setting the appropriate bits in the SLU Configuration Register or through the configuration menu. The baud rates are controlled in the same way.

You can connect the on-board SLUs to terminals, printers, or modems in three different ways. The first method is used when the QED 95 is installed in a PDP-11/24. The 11/24 has connections on the backplane to bring the RS232 signals from the MS95 memory board to a two-port distribution panel mounted on the system cabinet. The second method is via a Quickware cable assembly that connects to J3 on the memory board. The assembly consists of two RS232 cables attached to a 34-pin socket header. The RS232 termination occurs via standard DB25 male connectors. The third method is to use a Quickware Console Interface Module (CIM). These CIMs are either dual or quad boards that connect to J3 on the MS95 board via a ribbon cable. The CIM provides several types of connectors for use with Digital cables. The CIM also allows
CHAPTER 2. FEATURES

you to use 20mAmp devices. The CIM is also used to interface the MS95 memory board to various front panels.

2.2.2 On-board Clock

The on-board clock is compatible with the KW11, the standard Digital line clock used for system time. This same type of clock is found on the DL11-W, which is often used as the console terminal interface.

You can select the clock rate from four sources – 1) AC Line 2) 50 Hz crystal 3) 60 Hz crystal and 4) 800 Hz crystal. The AC line is the standard and most accurate over the long term.

2.2.3 Unibus Interface

The MS95, which acts as a host adapter to connect the QED 95 CPU with the Unibus, adheres strictly to the Digital Unibus standard referenced in the PDP-11 Bus Handbook. This ensures compatibility with all Digital peripherals.

2.2.4 Error-Correcting Memory

The MS95 includes 4 MB of Error-Correcting Code (ECC) memory. Using the parity CSR located at 172100, you can disable correction or enable parity-error traps.

An AMD 29C60 Error Detect and Correct chip performs the error-correction. This chip generates the check bits on writes and the error check and correction on reads. The AMD 29C60 detects and corrects all single-bit errors and detects all double-bit errors and most triple-bit errors. This sophisticated error correction scheme protects system integrity better than traditional error-checking techniques. It also increases the system up-time.

Memory reads and writes from the CPU are extremely fast, since they occur over the QMI bus. Reads occur in 400 nanoseconds. Writes occur even faster, by latching write data and allowing the CPU to continue execution before the write is complete.

If you are using the QED 95 system to replace an 11/04/34 or other system with 256 KB or less memory, the operating system may need to be re-sysgened in order to take advantage of the extra memory.

2.2.5 Unibus Map

Quickware has implemented the standard Unibus Map used in all Unibus systems with more than 256 KBytes of memory. The Unibus Map converts traditional 18-bit Direct Memory Access addresses to the 22-bit address space of newer PDP-11s. This allows the use of standard Unibus disk and tape controllers with the 4 MB memory of the
QED 95/MS95. The Unibus Map is supported by all DEC operating systems and is transparent to applications running under those operating systems. An additional feature allows you to disable parts of the Unibus Map in special applications. Use this feature when a peripheral device uses a window in memory for communicating with the application.

2.2.6 Battery Backup

Battery backup is supported via the standard DEC BBU option, except on the PDP-11/70. Using battery backup on the 11/70 requires the Quickware BB95 board and MS95 revision D or higher. The BB95, which has a sealed battery, can be used in other PDP-11 computers not equipped with a DEC battery backup unit.
3 System Configuration

The QED 95 is available in several configurations. While the basic design remains the same, the various configurations address slightly different system requirements and form factors required by the variety of DEC PDP-11 systems.

The QED 95 processor system consists of several boards.

<table>
<thead>
<tr>
<th>Module</th>
<th>Board Size</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU</td>
<td>Hex</td>
<td>CPU</td>
</tr>
<tr>
<td>95-AUX</td>
<td>Hex</td>
<td>Boot Logic and CPU Assist</td>
</tr>
<tr>
<td>95-MBA</td>
<td>Hex</td>
<td>Massbus Adapter for the 11/70</td>
</tr>
<tr>
<td>MS95</td>
<td>Hex</td>
<td>Memory</td>
</tr>
<tr>
<td>UB70</td>
<td>Quad</td>
<td>Unibus Connector for the 11/70</td>
</tr>
<tr>
<td>BB95</td>
<td>Quad</td>
<td>Battery Backup</td>
</tr>
<tr>
<td>CIM-44</td>
<td>Dual</td>
<td>Front Panel Interface for the 11/44</td>
</tr>
<tr>
<td>CIM-60</td>
<td>Quad</td>
<td>Front Panel Interface for the (11/04/34/35/40/60/70)</td>
</tr>
</tbody>
</table>

Some of these boards are not used in certain configurations.
## 3.1 QED 95A Modules to Upgrade the PDP-11/04

<table>
<thead>
<tr>
<th>Module</th>
<th>Board Size</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU</td>
<td>Hex</td>
<td>CPU</td>
</tr>
<tr>
<td>95-AUX</td>
<td>Hex</td>
<td>Boot Logic and CPU Assist</td>
</tr>
<tr>
<td>MS95</td>
<td>Hex</td>
<td>Memory</td>
</tr>
<tr>
<td>CIM-60 (optional)</td>
<td>Quad</td>
<td>Front Panel Interface</td>
</tr>
</tbody>
</table>

## 3.2 QED 95A Modules to Upgrade the PDP-11/24

<table>
<thead>
<tr>
<th>Module</th>
<th>Board Size</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU</td>
<td>Hex</td>
<td>CPU</td>
</tr>
<tr>
<td>95-AUX</td>
<td>Hex</td>
<td>Boot Logic and CPU Assist</td>
</tr>
<tr>
<td>MS95</td>
<td>Hex</td>
<td>Memory</td>
</tr>
</tbody>
</table>

## 3.3 QED 95A Modules to Upgrade the PDP-11/34

<table>
<thead>
<tr>
<th>Module</th>
<th>Board Size</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU</td>
<td>Hex</td>
<td>CPU</td>
</tr>
<tr>
<td>95-AUX</td>
<td>Hex</td>
<td>Boot Logic and CPU Assist</td>
</tr>
<tr>
<td>MS95</td>
<td>Hex</td>
<td>Memory</td>
</tr>
<tr>
<td>CIM-60 (optional)</td>
<td>Quad</td>
<td>Front Panel Interface</td>
</tr>
</tbody>
</table>

## 3.4 QED 95B Modules to Upgrade the PDP-11/35/40

<table>
<thead>
<tr>
<th>Module</th>
<th>Board Size</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU</td>
<td>Hex</td>
<td>CPU</td>
</tr>
<tr>
<td>95-AUX</td>
<td>Hex</td>
<td>Boot Logic and CPU Assist</td>
</tr>
<tr>
<td>MS95</td>
<td>Hex</td>
<td>Memory</td>
</tr>
<tr>
<td>CIM-60</td>
<td>Quad</td>
<td>Front Panel Interface</td>
</tr>
</tbody>
</table>
### 3.5 QED 95C Modules to Upgrade the PDP-11/44

<table>
<thead>
<tr>
<th>Module</th>
<th>Board Size</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU</td>
<td>Hex</td>
<td>CPU</td>
</tr>
<tr>
<td>95-AUX</td>
<td>Hex</td>
<td>Boot Logic and CPU Assist</td>
</tr>
<tr>
<td>MS95</td>
<td>Hex</td>
<td>Memory</td>
</tr>
<tr>
<td>CIM-44</td>
<td>Dual</td>
<td>Front Panel Interface</td>
</tr>
</tbody>
</table>

### 3.6 QED 95B Modules to Upgrade the PDP-11/60

<table>
<thead>
<tr>
<th>Module</th>
<th>Board Size</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU</td>
<td>Hex</td>
<td>CPU</td>
</tr>
<tr>
<td>95-AUX</td>
<td>Hex</td>
<td>Boot Logic and CPU Assist</td>
</tr>
<tr>
<td>MS95</td>
<td>Hex</td>
<td>Memory</td>
</tr>
<tr>
<td>CIM-60</td>
<td>Quad</td>
<td>Front Panel Interface</td>
</tr>
<tr>
<td>BB95 (optional)</td>
<td>Quad</td>
<td>Battery Backup</td>
</tr>
</tbody>
</table>

### 3.7 QED 95D Modules to Upgrade the PDP-11/70

<table>
<thead>
<tr>
<th>Module</th>
<th>Board Size</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU</td>
<td>Hex</td>
<td>CPU</td>
</tr>
<tr>
<td>95-AUX</td>
<td>Hex</td>
<td>Boot Logic and CPU Assist</td>
</tr>
<tr>
<td>95-MBA</td>
<td>Hex</td>
<td>Massbus Adapter</td>
</tr>
<tr>
<td>MS95</td>
<td>Hex</td>
<td>Memory</td>
</tr>
<tr>
<td>UB70</td>
<td>Quad</td>
<td>Unibus Connector</td>
</tr>
<tr>
<td>BB95 (optional)</td>
<td>Quad</td>
<td>Battery Backup</td>
</tr>
<tr>
<td>CIM-60 (optional)</td>
<td>Quad</td>
<td>Front Panel Interface</td>
</tr>
</tbody>
</table>
4 Jumper Configuration

The on-board devices are configured through the startup menu; however, several jumpers are provided for configuring the boards for installation in various systems.

4.1 95-CPU Board Jumpers

<table>
<thead>
<tr>
<th>Massbus Connection</th>
<th>Jumper</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>PDP-11/70</td>
<td>W2,W3,W4</td>
<td>In</td>
</tr>
<tr>
<td>PDP-11/04, 24, 34, 35, 40, 44, 60</td>
<td>W2,W3,W4</td>
<td>Out</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Bus Grants</th>
<th>Jumper</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>PDP-11/24</td>
<td>W5,W6,W8,W9,W10</td>
<td>In</td>
</tr>
<tr>
<td>PDP-11/04, 34, 35, 40, 44, 60, 70</td>
<td>W5,W6,W8,W9,W10</td>
<td>Out</td>
</tr>
</tbody>
</table>
4.2 95-AUX Board Jumpers

| 95-AUX Soldered Wire Jumper Selection. |
|-------------------------------|----------------|----------------|
| **See Page 17 for Jumper Layout** | **Jumper** | **Position** |
| Boot ROMs                     |              |               |
| All PDP-11s                   | W1,W5        | In            |
| All PDP-11s                   | W2,W4        | Out           |
| Massbus Connection            |              |               |
| PDP-11/70                     | W3,W12       | In            |
| PDP-11/04, 24, 34, 35, 40, 44, 60 | W3,W12   | Out           |
| Bus Grants                    |              |               |
| PDP-11/24                     | W6,W7,W8,W9,W11 | In     |
| PDP-11/04, 34, 35, 40, 44, 60, 70 | W6,W7,W8,W9,W11 | Out |
| Factory Test                  |              |               |
| All PDP-11s                   | W10          | Out           |

4.3 MS95 Memory Board Jumpers

The MS95 jumpers consist of both soldered wire jumpers and multi-post movable shunts. The factory default is not set for battery backup. The three-post shunts have two positions. If the shunt is installed on the two posts marked by **IN**, the jumper is active. If the shunt is installed on the middle post and the post marked **OUT** the jumper is inactive. Unused shunts may be stored in the inactive configuration.

<table>
<thead>
<tr>
<th>MS95 Jumpers for Battery Backup</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>See Page 17 for Jumper Layout</strong></td>
</tr>
<tr>
<td>No-Battery Backup</td>
</tr>
<tr>
<td>All PDP-11s</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Battery Backup</td>
</tr>
<tr>
<td>11/34, 44</td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>
### MS95 Jumpers to Select PDP-11 Backplane

<table>
<thead>
<tr>
<th>Backplane</th>
<th>Jumper</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>11/24</td>
<td>W8,9</td>
<td>Out</td>
</tr>
<tr>
<td></td>
<td>W1,2,3,4,5,6,7,10,56,57</td>
<td>In</td>
</tr>
<tr>
<td></td>
<td>RN2</td>
<td>In</td>
</tr>
<tr>
<td>11/04, 34</td>
<td>W8,9</td>
<td>In</td>
</tr>
<tr>
<td></td>
<td>W1,2,3,4,5,6,7,10,56,57</td>
<td>Out</td>
</tr>
<tr>
<td></td>
<td>RN2</td>
<td>Out</td>
</tr>
<tr>
<td>11/35, 40, 44, 60, 70</td>
<td>W8,9</td>
<td>Out</td>
</tr>
<tr>
<td></td>
<td>W1,2,3,4,5,6,7,10,56,57</td>
<td>Out</td>
</tr>
<tr>
<td></td>
<td>RN2</td>
<td>Out</td>
</tr>
</tbody>
</table>

### 4.4 CIM-44 Board Switches

<table>
<thead>
<tr>
<th>Switch</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>Communication Interface</td>
<td></td>
</tr>
<tr>
<td>RS232</td>
<td>Left</td>
</tr>
<tr>
<td>20 ma</td>
<td>Right</td>
</tr>
<tr>
<td>Console Receiver</td>
<td></td>
</tr>
<tr>
<td>Active 20 ma</td>
<td>Left</td>
</tr>
<tr>
<td>Passive 20 ma</td>
<td>Right</td>
</tr>
<tr>
<td>Console Transmitter</td>
<td></td>
</tr>
<tr>
<td>Active 20 ma</td>
<td>Left</td>
</tr>
<tr>
<td>Passive 20 ma</td>
<td>Right</td>
</tr>
</tbody>
</table>

### 4.5 CIM-60 Board Jumpers

The CIM-60 must be used with the PDP-11/35, 11/40, and 11/60, and it can be used with the PDP-11/04, 11/24, 11/34, or 11/70. The CIM-60 jumpers consist of soldered wire jumpers, removable post shunts and miniature slide switches.
## CIM-60 Jumper Selection

<table>
<thead>
<tr>
<th>Bus Grants</th>
<th>Jumper</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>11/04, 24, 34</td>
<td>W16, 17, 18, 19, 20</td>
<td>In</td>
</tr>
<tr>
<td>11/35, 40, 60, 70</td>
<td>W16, 17, 18, 19, 20</td>
<td>Out</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PDP-11/60 Connections</th>
<th>Jumper</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>11/60</td>
<td>W3, 4, 5, 6, 7, 8, 9, 10, 11</td>
<td>In</td>
</tr>
<tr>
<td>11/04, 24, 34, 35, 40, 70</td>
<td>W3, 4, 5, 6, 7, 8, 9, 10, 11</td>
<td>Out</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Factory Test</th>
<th>Jumper</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>All PDP-11s</td>
<td>W12, 13, 14, 15</td>
<td>Out</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Power +15 Volts</th>
<th>Jumper</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>11/04, 34</td>
<td>W1, W2</td>
<td>In</td>
</tr>
<tr>
<td></td>
<td>U5</td>
<td>Out</td>
</tr>
<tr>
<td>11/24, 35, 40, 60, 70</td>
<td>W1, W2</td>
<td>Out</td>
</tr>
<tr>
<td></td>
<td>U5</td>
<td>In</td>
</tr>
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</table>

## CIM-60 Switch Selection

<table>
<thead>
<tr>
<th>Communication Interface</th>
<th>Switch</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>RS232</td>
<td>1</td>
<td>Left</td>
</tr>
<tr>
<td>20 ma</td>
<td></td>
<td>Right</td>
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</tbody>
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<table>
<thead>
<tr>
<th>Console Transmitter</th>
<th>Switch</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>Active 20 ma</td>
<td>2</td>
<td>Left</td>
</tr>
<tr>
<td>Passive 20 ma</td>
<td></td>
<td>Right</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Console Receiver</th>
<th>Switch</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>Active 20 ma</td>
<td>3</td>
<td>Left</td>
</tr>
<tr>
<td>Passive 20 ma</td>
<td></td>
<td>Right</td>
</tr>
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</table>

<table>
<thead>
<tr>
<th>SLU2 Transmitter</th>
<th>Switch</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>Active 20 ma</td>
<td>4</td>
<td>Left</td>
</tr>
<tr>
<td>Passive 20 ma</td>
<td></td>
<td>Right</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>SLU2 Receiver</th>
<th>Switch</th>
<th>Position</th>
</tr>
</thead>
<tbody>
<tr>
<td>Active 20 ma</td>
<td>5</td>
<td>Left</td>
</tr>
<tr>
<td>Passive 20 ma</td>
<td></td>
<td>Right</td>
</tr>
</tbody>
</table>
CHAPTER 4. JUMPER CONFIGURATION

95-MBA

UB70
5 Installation

Each of the following sections describes how to install your QED 95 system in one of the PDP-11 models. Please read the directions carefully, and do not force any boards or cables during the installation process.

We recommend that you check the system power supplies after completing the installation, since the QED boards typically put a smaller load on the power supplies, and this may change the voltage output. If you are not familiar with this procedure, wait until a service technician can do it on a preventative maintenance visit. The acceptable range for voltage is from 4.75 to 5.25 volts; however, we consider an ideal voltage to be between 5.00 and 5.15 volts. The details for adjusting the power supplies of a PDP-11/70 can be found in section 5.7.1.

5.1 QED 95A Installation in the PDP-11/04

The design of the QED 95A allows you to replace the PDP-11/04 processor module (11/04 M7263).

1. See chapter four for information on jumper and switch settings for board setup.
2. Exercise the PDP-11/04 system to ensure that it is operating properly.
3. Turn off all power to the system.
4. Ensure that the cabinet is properly stabilized before sliding the processor box out.
5. Open the processor box. Remove the CPU module from slot one.
6. If the M9312 Boot terminator module is installed, remove it.
7. Remove all the memory modules.
8. Install the 95-CPU Processor board in slot one.
9. Install the 95-AUX Auxiliary board in slot two.
10. Install the MS95 Memory board in slot three.
11. If you are installing the *optional* CIM-60 (Console Interface Module) insert it in slot four, rows C-F. Consult section 5.9 for the CIM-60 cable installation.

12. Ensure that a Bus Grant Module (G727A) is inserted in any empty slot.
13. Install the cables that connect the 95-CPU, 95-AUX, and MS95 boards. First, use the 60 pin ribbon cable that has three connectors to interconnect the J1 connectors on the three boards. Next, connect the 34 pin ribbon cable between the J2 connectors on the 95-AUX and the MS95. Connect the 60 pin ribbon cable between the J3 connectors on the 95-CPU and the 95-AUX.
14. Close the processor box and push it back into the cabinet. Make sure that no cables are pinched or strained as the system box is slid back into place. Turn on all the power.
15. After you turn on the power, the CPU will run self-test diagnostics. This will take approximately 15 seconds. As the tests run, the LEDs on the AUX will cycle. Also, a series of periods will be sent to the terminal. When the tests
complete, a prompt ">" is sent to the terminal asking for a carriage return. This carriage return is used to synchronize the baud rates. The first time the system is installed, several carriage returns at one second intervals may be necessary. The configuration menu will then be displayed. See chapter six for more information on using the menu.

16. The QED 95 processor addresses 4 MB of memory. To use this amount of memory requires an operating system that uses the extra memory. If your old system had 256 KB or less, then you will likely need to generate a new operating system in order to use more than 256 KB of memory. To generate a new operating system, refer to your Digital operating system manual.

5.2 QED 95A Installation in the PDP-11/24

The design of the QED 95A allows you to replace the PDP-11/24 processor (M7133) and the KT24 (7134) Unibus Map modules.

1. See chapter four for information on jumper and switch settings for board setup. Verify that the jumper shunts are located properly for PDP-11/24 operation as described in section 4.3. The factory default is for a PDP-11/34.

2. Exercise the PDP-11/24 system to ensure that it is operating properly.

3. Turn off all power to the system.

4. Ensure that the cabinet is properly stabilized before sliding the processor box out.

5. Open the processor box. Remove the boards (M7133 and M7134) located in slots 1 and 2.

6. If the M9312 Boot terminator module is installed, remove it.

7. Remove all the memory modules.

8. Install the 95-CPU Processor board in slot three.

9. Install the 95-AUX Auxiliary board in slot two.

10. Install the MS95 Memory board in slot one.

11. Ensure that a Bus Grant Module (G727A) is inserted in any empty slot.

12. Install the cables that connect the 95-CPU, 95-AUX, and MS95 boards. First, use the 60 pin ribbon cable that has three connectors to interconnect the J1 connectors on the three boards. Next, connect the 34 pin ribbon cable between the J2 connectors on the 95-AUX and the MS95. Connect the 60 pin ribbon cable between the J3 connectors on the 95-CPU and the 95-AUX.
13. Close the processor box and push it back into the cabinet. Make sure that no
cables are pinched or strained as the system box is slid back into place. Turn on
all the power.

14. After you turn on the power, the CPU will run self-test diagnostics. This will
take approximately 15 seconds. As the tests run, the LEDs on the AUX will
cycle. Also, a series of periods will be sent to the terminal. When the tests
complete, a prompt “>” is sent to the terminal asking for a carriage return. This
carriage return is used to synchronize the baud rates. The first time the system is
installed, several carriage returns at one second intervals may be necessary. The
configuration menu will then be displayed. See chapter six for more information
on using the menu.

15. The QED 95 processor addresses 4 MB of memory. To use this amount of
memory requires an operating system that uses the extra memory. If your old
system had 256 KB or less, then you will likely need to generate a new operating
system in order to use more than 256 KB of memory. To generate a new
operating system, refer to your Digital operating system manual.
5.3 QED 95A Installation in the PDP-11/34

The design of the QED 95A allows you to replace the PDP-11/34 processor modules (11/34: M7266, M7265) or (11/34A: M8266, M8265).

1. See chapter four for information on jumper and switch settings for board setup.
2. Exercise the PDP-11/34 system to ensure that it is operating properly.
3. Turn off all power to the system.
4. Ensure that the cabinet is properly stabilized before sliding the processor box out.
5. Open the processor box. Remove the CPU modules from slots one and two. If the optional floating point board or cache memory board is installed, remove these also.
6. If the M9312 Boot terminator module is installed, remove it.
7. Remove all the memory modules.
8. Install the 95-CPU Processor board in slot one.
9. Install the 95-AUX Auxiliary board in slot two.
10. Install the MS95 Memory board in slot three.
11. If you are installing the optional CIM-60 (Console Interface Module) insert it in slot four, rows C-F. Consult section 5.9 for the CIM-60 cable installation.
12. Ensure that a Bus Grant Module (G727A) is inserted in any empty slot.
13. Install the cables that connect the 95-CPU, 95-AUX and MS95 boards. First, use the 60 pin ribbon cable that has three connectors to interconnect the J1 connectors on the three boards. Next, connect the 34 pin ribbon cable between the J2 connectors on the 95-AUX and the MS95. Connect the 60 pin ribbon cable between the J3 connectors on the 95-CPU and the 95-AUX.
14. Close the processor box and push it back into the cabinet. Make sure that no cables are pinched or strained as the system box is slid back into place. Turn on all the power.
15. After you turn on the power, the CPU will run self-test diagnostics. This will take approximately 15 seconds. As the tests run, the LEDs on the AUX will cycle. Also, a series of periods will be sent to the terminal. When the tests complete, a prompt “>” is sent to the terminal asking for a carriage return. This carriage return is used to synchronize the baud rates. The first time the system is
installed, several carriage returns at one second intervals may be necessary. The configuration menu will then be displayed. See chapter six for more information on using the menu.

16. The QED 95 processor addresses 4 MB of memory. To use this amount of memory requires an operating system that uses the extra memory. If your old system had 256 KB or less, then you will likely need to generate a new operating system in order to use more than 256 KB of memory. To generate a new operating system, refer to your Digital operating system manual.

5.4 QED 95B Installation in the PDP-11/35/40

The design of the QED 95B allows you to replace the PDP-11/35/40 processor modules M7231 through M7239.

1. See chapter four for information on jumper and switch settings for board setup.
2. Exercise the PDP-11/35/40 system to ensure that it is operating properly.
3. Turn off all power to the system.
4. Ensure that the cabinet is properly stabilized before sliding the processor box out.

5. Open the processor box. Remove all the modules in slots one to nine of the processor backplane, making sure to identify and mark the two cables which connect the front panel to the Data Path (M7231) and Status boards (M7235). Remove all the memory modules located in the four-slot memory backplane.

6. First, install the MS95 Memory board in slot one of the memory backplane.

7. Install the 95-AUX Auxiliary board in slot nine.

8. Install the 95-CPU Processor board in slot eight.

9. Install the CIM-60 Console Interface Module (quad board) in slot seven, rows C-F. Consult section 5.9 for the CIM-60 cable installation. It will be helpful to install the two front panel cables on the CIM-60 before installing it in
the backplane. These cables are installed facing the same way as they did previously, with the Data Path cable in J2, and the Status cable, in J1. Insert the long 34-pin cable between J3 on the CIM-60 and J3 on the MS95. Connect the DL-11 cable to J4.

10. Ensure that a Bus Grant Module (G727A) is inserted in any empty slot of the memory backplane.

11. Install the cables that connect the 95-CPU, 95-AUX and MS95 boards. First, use the 60 pin ribbon cable that has three connectors to interconnect the J1 connectors on the three boards. Next, connect the 34 pin ribbon cable between the J2 connectors on the 95-AUX and the MS95. Connect the 60 pin ribbon cable between the J3 connectors on the 95-CPU and the 95-AUX.

12. Close the processor box and push it back into the cabinet. Make sure that no cables are pinched or strained as the system box is slid back into place. Turn on all the power. The Run and Proc lights on the front panel should now be on. Both lights will go out whenever the machine is halted, and the computer is in ODT. (Note: When using the CIM-60 only two switches on the front panel are active. The Halt switch for halting the computer, and the Start switch for rebooting.)

13. After you turn on the power, the CPU will run self-test diagnostics. This will take approximately 15 seconds. As the tests run, the LEDs on the AUX will cycle. Also, a series of periods will be sent to the terminal. When the tests complete, a prompt “>>” is sent to the terminal asking for a carriage return. This carriage return is used to synchronize the baud rates. The first time the system is installed, several carriage returns at one second intervals may be necessary. The configuration menu will then be displayed. See chapter six for more information on using the menu.

14. The QED 95 processor addresses 4 MB of memory. To use this amount of memory requires an operating system that uses the extra memory. If your old system had 256 KB or less, then you will likely need to generate a new operating system in order to use more than 256 KB of memory. To generate a new operating system, refer to your Digital operating system manual.

5.5 QED 95C Installation in the PDP-11/44

The design of the QED 95C allows you to replace the PDP-11/44 processor modules M7090 through 7098.

1. See chapter four for information on jumper and switch settings for board setup.
2. Exercise the PDP-11/44 system to ensure that it is operating properly.
3. Turn off all power to the system.

**QED 95 C Processor upgrade**

*Layout in PDP-11/44 Backplane*

<table>
<thead>
<tr>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
<th>E</th>
<th>F</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>CIM-44</td>
<td>CONSOLE INTERFACE MODULE</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Vacant</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>Vacant</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>Vacant</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>Vacant</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>Vacant</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>95-CPU</td>
<td>PROCESSOR BOARD</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>Vacant</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>95-AUX</td>
<td>AUXILIARY BOARD</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>Vacant</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>11</td>
<td>Vacant</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>12</td>
<td>MS 95</td>
<td>MEMORY BOARD</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>13</td>
<td>SPC</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>14</td>
<td>M9302, M9202, BC11-A</td>
<td>SPC</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

4. Ensure that the cabinet is properly stabilized before sliding the processor box out.

5. Open the processor box. Remove all the modules in slots one through eight, and all the memory modules.

6. Install the 95-CPU Processor board in slot seven.

7. Install the 95-AUX Auxiliary board in slot nine.

8. Install the MS95 Memory board in slot twelve.

9. Install the CIM-44 Console Interface Module (dual board) in slot 1, rows A-B. Consult section 5.8 for the CIM-44 cable installation.

10. Install the cables that connect the 95-CPU, 95-AUX, and MS95 boards. First, use the 60 pin ribbon cable that has three connectors to interconnect the J1 connectors on the three boards. Next, connect the 34 pin ribbon cable between the J2 connectors on the 95-AUX and the MS95. Connect the 60 pin ribbon cable between the J3 connectors on the 95-CPU and the 95-AUX.

11. Close the processor box and push it back into the cabinet. Make sure that no cables are pinched or strained as the system box is slid back into place. Turn on all the power.

12. After you turn on the power, the CPU will run self-test diagnostics. This will take approximately 15 seconds. As the tests run, the LEDs on the AUX will
cycle. Also, a series of periods will be sent to the terminal. When the tests complete, a prompt “>” is sent to the terminal asking for a carriage return. This carriage return is used to synchronize the baud rates. The first time the system is installed, several carriage returns at one second intervals may be necessary. The configuration menu will then be displayed. See chapter six for more information on using the menu.

5.6 QED 95B Installation in the PDP-11/60

The design of the QED 95B allows you to replace the PDP-11/60 processor modules M7870 through M7881.

1. See chapter four for information on jumper and switch settings for board setup.
2. Exercise the PDP-11/60 system to ensure that it is operating properly.
3. Turn off all power to the system.
4. Ensure that the cabinet is properly stabilized before sliding the processor box out.
5. Open the processor box. Remove all the modules in slots 1 through 12. Remove the Unibus cable which goes to the memory backplane.
6. Install the 95-CPU Processor board in slot nine.
7. Install the 95-AUX Auxiliary board in slot ten.
8. Install the MS95 Memory board in slot twelve.
9. Install the CIM-60 Console Interface Module (quad board) in slot seven, rows C-F. Consult section 5.9 for the CIM-60 cable installation.
10. If you are installing the optional BB95 (Battery Backup Board) insert it in slot five, rows C-F.
11. Install the cables that connect the 95-CPU, 95-AUX, and MS95 boards. First, use the 60 pin ribbon cable that has three connectors to interconnect the J1 connectors on the three boards. Next, connect the 34 pin ribbon cable between the J2 connectors on the 95-AUX and the MS95. Connect the 60 pin ribbon cable between the J3 connectors on the 95-CPU and the 95-AUX.
12. Make sure that a Bus Grant Module (G727A) is inserted in slots 13 and 14 unless these slots are occupied by an SPC unit.
13. Close the processor box and push it back into the cabinet. Make sure that no cables are pinched or strained as the system box is slid back into place. Turn on all the power.

14. After you turn on the power, the CPU will run self-test diagnostics. This will take approximately 15 seconds. As the tests run, the LEDs on the AUX will cycle. Also, a series of periods will be sent to the terminal. When the tests complete, a prompt “>” is sent to the terminal asking for a carriage return. This carriage return is used to synchronize the baud rates. The first time the system is installed, several carriage returns at one second intervals may be necessary. The configuration menu will then be displayed. See chapter six for more information on using the menu.

15. The QED 95 processor addresses 4 MB of memory. To use this amount of memory requires an operating system that uses the extra memory. If your old system had 256 KB or less, then you will likely need to generate a new operating system in order to use more than 256 KB of memory. To generate a new operating system, refer to your Digital operating system manual.
5.7 QED 95D Installation in the PDP-11/70

The design of the QED 95D allows you to replace the PDP-11/70 processor modules M8112 through M8115, and M8130 through M8145.

1. See chapter four for information on jumper and switch settings for board setup.
2. Exercise the PDP-11/70 system to ensure that it is operating properly.
3. Turn off all power to the system.
4. Ensure that the cabinet is properly stabilized before sliding the processor box out.
5. Open the processor box. Remove all the modules in slots 1 through 22. As you remove modules M8134 and M8140, identify and mark the three cables which connect them to the front panel. As you remove modules M8143 and M8145, remove the four cables to the memory chassis; they are no longer needed.
6. Install the 95-MBA Massbus Adapter board in slot 21. Connect the three cables from the front panel to it. These formerly went to the M8134 and M8140 boards. Notice that the markings on the board indicate which connector is for each cable.
7. Connect the two 50 conductor cables (2 ft long) to the MS95 board, using connectors J4 and J5, along the bottom edge. Install the MS95 Memory board in slot 14.
8. Install the 95-CPU Processor board in slot 17.
9. Install the 95-AUX Auxiliary board in slot 18.
10. Connect the two 50 conductor cables from the MS95 to the UB70. Connect the Boot cable and the Boot Enable cable which were connected to the M9301 to the UB70. Install the UB70 Unibus Adapter (quad board) in slot one, rows C-F.
11. If you are installing the optional CIM-60 (Console Interface Module), insert it in slot twelve, rows C-F. Consult section 5.9 for the CIM-60 cable installation.
12. If you are installing the optional BB95 (Battery Backup Board) install it in slot ten, rows C-F.
13. Install the cables that connect the 95-CPU, 95-AUX, MS95, and the 95-MBA boards. The 34 pin cable connects J2 on the MS95 to J2 on the 95-AUX. Next, install the 60 pin cable with 4 connectors by connecting it to J1 on the MS95 first, then the 95-CPU, next the 95-AUX, and finally the 95-MBA. This will allow the cable to fold the right way, for easiest installation. The 60 pin cable with 3 connectors is installed in a similar fashion, among the J3 connectors on the 95-CPU, 95-AUX, and 95-MBA.

14. If you will be using your existing DL-11, leave it in place. If not, you may remove it and replace it with a grant card, and install the cable with a 34 pin connector and two RS-232 ends. The 34 pin end connects to J3 on the MS95, and the two DB-25 (RS-232) connectors can be routed to the console and an optional second serial port.

15. Close the processor box and push it back into the cabinet. Make sure that no cables are pinched or strained as the system box is slid back into place. Turn on all the power.

16. After you turn on the power, the CPU will run self-test diagnostics. This will take approximately 15 seconds. As the tests run, the LEDs on the AUX will cycle. Also, a series of periods will be sent to the terminal. When the tests complete, a prompt “>” is sent to the terminal asking for a carriage return.
carriage return is used to synchronize the baud rates. The first time the system is installed, several carriage returns at one second intervals may be necessary. The configuration menu will then be displayed. See chapter six for more information on using the menu.

5.7.1 Adjusting the PDP-11/70 Power Supplies

We recommend that you adjust the system power supplies after installing the QED 95. This section describes the 11/70 power supplies, and is included because there are so many regulators, and because you will likely see a measurable difference in the voltage levels after installing the QED 95, due to the large number of 11/70 boards replaced.

As the drawing illustrates, there are two H7420 power supplies in the main 11/70 chassis. Each H7420 has 4 regulators installed, and one empty regulator position. (In systems which did not have floating point, the A regulator of the upper H7420 may be missing.) The four regulators in the upper H7420 are called A through D, and the lower regulators are called H,J, K and L. Each of these regulators may be either an H744, H7440, or an H7441.

Each regulator supplies power to different slots in the backplane, according to the following table. As the table shows, Regulators B,C,J and H are now powering QED equipment. Regulators C,K, and L provide power to Unibus and RH70 (Massbus) peripherals in the main backplane.

<table>
<thead>
<tr>
<th>Regulator</th>
<th>Backplane slots powered</th>
<th>Devices which use it</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>Slots 2-5</td>
<td>(was for 11/70 FP)</td>
</tr>
<tr>
<td>B</td>
<td>Slots 1,6-9</td>
<td>UB70</td>
</tr>
<tr>
<td>C</td>
<td>Slots 10-15</td>
<td>QED MS95</td>
</tr>
<tr>
<td>D</td>
<td>Slots 36-44</td>
<td>(RH70 D and Unibus)</td>
</tr>
<tr>
<td>J</td>
<td>Slots 16-18</td>
<td>QED CPU and AUX</td>
</tr>
<tr>
<td>H</td>
<td>Slots 20-22</td>
<td>QED MBA</td>
</tr>
<tr>
<td>K</td>
<td>Slots 24-28</td>
<td>(RH70 A-B)</td>
</tr>
<tr>
<td>L</td>
<td>Slots 29-35</td>
<td>(RH70 B-C)</td>
</tr>
</tbody>
</table>

When you adjust a regulator, measure the +5V line on the backplane at a spot corresponding to the slots which the regulator powers. **WARNING! You can easily destroy boards if you adjust a regulator while monitoring the wrong voltage.** You will probably notice the greatest change on the A,B,C, J and H regulators, since the load on these has been reduced by installing the QED 95 system.
All voltages should be adjusted to be within 4.75 to 5.25 volts, and between 5.00 and 5.15 volts is ideal.

```
  D  C  B  A
(empty) H774x H774x H774x H774x
                  (may be empty, if FP was not installed.)
```

```
  H774x H774x H774x H774x (empty)
  L  K  J  H
```

PDP-11/70 Power supplies

### 5.8 CIM-44 Cable Installation

Connect J5 to MS95-J3 Memory Board with 34 pin ribbon cable.
Reconnect front panel cable (Digital) to J5.
Reconnect console terminal cable to J2.
Reconnect optional second serial unit or TU58 to J4.
Reconnect optional DEC remote diagnostic cable to J3.
5.9 CIM-60 Cable Installation

For all PDP-11s:

Connect CIM-60-J3 to MS95-J3 with 34 pin ribbon cable.
Reconnect Console Terminal Cable to J4.
Reconnect Optional second DL11 cable to J5.

For PDP-11/04, 34s with KY11-LB front panels:
Remove the M7859 and connect the KY11-LB cable to the CIM-60-J6.

For PDP-11/35, 40s:

Reconnect the 40 pin cable from the front panel to J2
(formerly went to the 11/40 Data Path board, M7231).
Reconnect the 40 pin cable from front panel to J1
(formerly went to the 11/40 Status board, M7235).
6 Startup & Configuration Menu

6.1 Front Panel Operation

6.1.1 PDP 11/04 or 34 Front Panel

**KY11-LA Operator's Console**
The KY11-LA operator's console is completely functional. To reboot, press the Boot/Init switch. To halt the processor put the Halt/Cont switch in the Halt position. This will put the QED 95 into ODT. To exit out of ODT and continue processing, place the Halt/Cont switch in the Cont position and press the “P” key on the console terminal. See chapter eight for further information on using ODT to examine and deposit memory.

**KY11-LB Programmer's Console**
The KY11-LB programmer's console is partially functional. The Halt, Continue and Boot keys are active and function normally. To reboot the system, press Ctrl-Halt then Ctrl-Boot. The programmer's console may not be used to access memory or Unibus devices. Instead, this is accomplished through the QED 95's ODT by halting the processor with Ctrl-Halt. To exit out of ODT and continue processing, press Ctrl-Cont then press the “P” key on the console terminal. See chapter eight for further information on using ODT to examine and deposit memory.

6.1.2 PDP 11/24 Front Panel

The 11/24 front panel is completely functional when the MS95 has been installed in slot one of the backplane. To reboot, press the Halt/Cont/Boot switch to the Boot position. To halt the processor put the Halt/Cont/Boot switch in the Halt position. This will put the QED 95 into ODT. To exit out of ODT and continue processing,
restore the Halt/Cont/Boot switch to the Cont position and press the "P" key on the console terminal. See chapter eight for further information on using ODT to examine and deposit memory.

6.1.3 PDP 11/35 or 40 Front Panel

The 11/35 front panel is partially functional. The Halt and Start switches are in use. The Run and Proc lights on the front panel will be on when the system is running, and both lights will go out whenever the machine is halted, and computer is in ODT. To reboot the system, press the Start switch. The programmer's console may not be used to access memory or Unibus devices. Instead, this is accomplished through the QED 95's ODT by halting the processor with the Halt switch. To exit out of ODT and continue processing, restore the Halt/Enable switch to the Enable position, then press the "P" key on the console terminal. See chapter eight for further information on using ODT to examine and deposit memory.

6.1.4 PDP 11/44 Front Panel

The 11/44 front panel will work when the CIM-44 has been installed in slot one of the backplane and connected to the MS95. To reboot, press the Halt/Cont/Boot switch to the Boot position. To halt the processor put the Halt/Cont/Boot switch in the Halt position. This will put the QED 95 into ODT. To exit out of ODT and continue processing, restore the Halt/Cont/Boot switch to the Com position and press the "P" key on the console terminal. See chapter eight for further information on using ODT to examine and deposit memory. Note that the RUN light on the 11/44 front panel does not function with the QED 95.

6.1.5 PDP 11/60 Front Panel

The 11/60 front panel will function in a limited way when used with the CIM-60. Only two switches on the front panel are active, the Halt button, which will halt the machine, and the Ctrl-Boot buttons, which will reboot the machine. The front panel numeric lights will indicate 222222 when the machine is halted, 333333 during DMA, and 777777 when the CPU is running. The programmer's console may not be used to access memory or Unibus devices. Instead, this is accomplished through the QED 95's ODT by halting the processor with the Halt switch. To exit out of ODT and continue processing, type the "P" key on the console terminal. See chapter eight for further information on using ODT to examine and deposit memory.

6.1.6 PDP 11/70 Front Panel

The 11/70 front panel has some limited use when connected to the QED 95 via the MBA board. The Halt switch will halt the CPU, and allow you to use the QED 95's
ODT to examine and deposit memory. ODT uses the console terminal instead of the lights and switches of the front panel; refer to chapter eight for more information on using ODT.

The 16 LEDs in the Data section of the front panel will display any value written to either the Display Register (at 177570) or to the Boot Display Register (at 177524). In this way, the diagnostic LED patterns which are displayed on the 16 AUX board LEDs are also displayed on the front panel. When a value is written to the Boot Display Register, (the AUX board LEDs at 177524) the value displayed on the 11/70 front panel is the inverted value (a lit LED indicates a 0, while a dark LED indicates a 1.) See Appendix C for a listing of the diagnostic LED codes.

The 16 data switches (0-15) on the front panel are active, and read as the Switch Register (177570). In this way, diagnostic programs which read the Switch Register and write to the Display Register can still function normally. The only other switch on the front panel which is active is the Halt Switch. Make sure that the Halt switch is not in the halt position when you try to boot the machine, or else the QED 95 will halt before it has had a chance to initialize itself. It is a useful and common practice with PDP-11/70's to power them off with the Halt switch in the halt position, but when you power up the QED 95, you must make sure that the halt switch is not still on.

Note that the status display LEDs on the front panel are not active (Run, Kernel, Master, etc.)

6.2 Bootstrapping the System

The QED 95 has two diagnostic/boot ROMs on-board. The diagnostics run when the power is turned on or the system is rebooted. These diagnostics take 15 seconds to complete. As the tests execute, the LEDs cycle. If an error is encountered, the system will halt, and the code displayed by the LEDs will indicate the type of error which occurred. Appendix C lists the LED codes. At the end of the tests, if the system is coming up for the first time (a cold boot), the memory is cleared and periods "." are printed at the console terminal. After the built-in diagnostics are complete and the memory is initialized, the ROMs print a ">" prompt and wait for several carriage returns from the console terminal to determine its baud rate. If you are using an existing DL11 interface for the console terminal, there is no need to determine the baud rate, and so the program will move on to the next step.

Next, the menu program is loaded into memory, starting at location 100000. The menu will print either the full menu or the device prompt. If you receive the device prompt and wish to run the full menu, type "QM" [RETURN] to see the full menu. The first time you run the QED 95 in a system, you should use the full menu to verify the correct settings.
Full Menu Screen Display:

QED90/95 Configuration Program
Copyright Quickware Inc., 1988-1991
Version 2.02

Cache memory fully ENABLED
4 MB on-board memory
Boot to: MENU
[Additional parameters here...]
...
1 = Restore Default Settings
2 = Customize Settings
V = Display Version
H = Halt to ODT
X = Exit
Selection: _

Boot Device Screen Display:

QED90/95 Configuration Program
Copyright Quickware Inc., 1988-1991
Version 2.02

Boot Device [DLO] ? _

Section 6.3 below explains the various options of the full configuration menu. To boot a disk or tape when you are in the full menu, select the “P” option. The prompt “Boot Device?” will then be displayed. If you type a question mark “?” the system will display a list of supported boot devices. Those device whose CSRs are found at standard locations are displayed in parentheses. The device “QM” is the Quickware Menu. Typing QM [RETURN] will return to the menu. Any other device code may be typed. All boot ROMs default to unit zero. This may be overridden by designating the desired unit.
Examples of responses to the Boot Device prompt:

QM [RETURN]
Displays the main menu for configuration.

DL [RETURN]
Boots RL01/02 unit zero.

DL2 [RETURN]
Boots RL01/02 unit two.

When you enter a valid boot command, the menu asks if you would like to save the command as the default. Typing "Y" will save the command. Typing "N" or [RETURN] will not save it.

The program will then attempt to boot the requested device. If the device is not ready, the message "Retrying. Type ^C to abort retries." will be displayed. If you wish to abort the command, type the "C" key while holding the CTRL key down. This will return you to the previous prompt; otherwise the program will continue to retry the device until it succeeds in booting.

When control is transferred to the operating system, the message "Booting..." will be displayed.

6.3 Using the Configuration Menu

The configuration menu is used in place of switches to set up the QED 95. The menu controls on-board Serial Line Units, on-board clock, memory size, and action to take at boot time.

This section will describe each of the menu options and sub-menus in turn.

6.3.1 Restore Default Settings

This option of the main menu allows you to easily set up the QED 95 for typical configurations. Seven standard configurations are presented, allowing you to choose which type of system the QED 95 is installed in, and which processor the QED 95 should emulate. There are four distinct systems in which the QED 95 may be installed, as follows: 1) PDP 11/24 systems, 2) PDP 11/44 systems, 3) PDP 11/70 systems and 4) all other systems. In 11/44 and 11/70 systems, you also have a choice of the processor emulation. You may choose to have the QED 95 emulate the original processor, or, for certain applications, you may want the QED 95 to emulate a J-11 processor instead. In 11/24 and all other systems (excepting 44s and 70s) the QED 95 will emulate a J-11 processor. The table on the next page describes the default settings.
We recommend that if you have an 11/44, you choose the normal 11/44 emulation, rather than the J-11 emulation. Also, if you have an 11/70, we recommend that you choose the 11/70 (A/full) emulation, rather than the C/J11 option or the B/Limited MMU option.

<table>
<thead>
<tr>
<th>Option</th>
<th>11/24,44</th>
<th>11/70, other</th>
</tr>
</thead>
<tbody>
<tr>
<td>SLU 1</td>
<td>Enabled</td>
<td></td>
</tr>
<tr>
<td>Halt on Break</td>
<td>Enabled</td>
<td>note 1</td>
</tr>
<tr>
<td>SLU 2</td>
<td>Enabled 9600 Baud</td>
<td>Disabled</td>
</tr>
<tr>
<td>Line Clock</td>
<td>Enabled, Line Clock</td>
<td>Disabled</td>
</tr>
<tr>
<td>Boot Action</td>
<td>Device Prompt</td>
<td>Device Prompt</td>
</tr>
<tr>
<td>Auto-Baud T.O.</td>
<td>No Time Out</td>
<td>No Time Out</td>
</tr>
<tr>
<td>Memory</td>
<td>All available QED memory</td>
<td>All available QED memory</td>
</tr>
<tr>
<td>Processor</td>
<td>note 3</td>
<td>note 3</td>
</tr>
</tbody>
</table>

Notes:
1. If the system has a DL11 console board, such as the DL11-W (M7856), the on-board SLU 1 is disabled; otherwise the SLU 1 is enabled and the baud rate is set automatically at boot time.
2. If the system has a KW11-compatible clock, such as on the DL11-W (M7856), the on-board clock is disabled; otherwise the on-board clock is enabled and set to use the clock pulse provided on the backplane.
3. When you choose an 11/24 or other PDP-11, the QED 95 will emulate a J-11 processor. When you choose an 11/44, you can choose to emulate either an 11/44 processor or the J-11. When you choose an 11/70, you can choose to emulate either a J-11, or an 11/70 with a full or a limited MMU.

### 6.3.2 Display Version

This option displays the current version of the Boot Roms and the Menu program. Section 6.4 lists the changes in each version.

### 6.3.3 Display Settings

This option displays the settings you have currently chosen. Note that if you have changed settings, they will not be saved and made permanent until you select the Save Configuration option. A message will be displayed to indicate that you have modified the configuration, and that you should save it to allow the changes to take effect.
6.3.4 Save Configuration

After you have made your selections, store the configuration in the EEROM by choosing this option. Please note that the settings will not take effect if you exit the menu without first saving the changes. The message "Configuration has been modified, remember to Save it." will display in the main menu whenever there are unsaved changes.

6.3.5 Proceed to Boot Prompt

The boot prompt allows you to select a device for booting. The prompt "Boot device {{DD0}} ?" asks you for the device to boot. The current default, if any, will be displayed in the "[]" brackets. Pressing RETURN selects the default. You can override the default by typing the device code and an optional unit number followed by RETURN. (Example DL2). If a device is entered, the question "Save for later auto-boot?" will ask if you want to store the device code as the new default.

To see a list of supported and installed devices type a "?". All available boot programs are displayed, including those in any M9312 that is installed. Devices that are installed at standard addresses are displayed in parentheses "()". The table on the next page shows the boot programs provided.

In addition to booting the devices at the standard addresses, a device installed at an alternate address may be booted using the \A:n option. If, for instance, a second RM02 controller was installed at address 176300, drive zero on this second controller could be booted using the syntax "DB0/A:176300", while drive three would be booted using "DB3/A:176300".

Some devices from third parties come with boot roms on their controller boards. If you want to boot using these roms, you would use the FB device code to indicate a "foreign boot rom" and specify the boot starting address using the \A:n option. For example, to boot a controller rom that is at address 171000, you would use the command "FB/A:171000".

If you need to boot a device which is not supported by the Quickware Boot Roms (see the next page for the table of supported devices), and you do not have a separate boot rom for it, you can enter the boot program into the EEPROM, where it will be stored, and can be run at boot time by using the UUn pseudo-device code. Four user boot programs, UU0 through UU3, may be stored in the EEPROM. See section 6.3.8.5 for more information on writing and storing user boot programs.
## CHAPTER 6. STARTUP & CONFIGURATION MENU

<table>
<thead>
<tr>
<th>Code</th>
<th>Device</th>
<th>Address of CSR</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>QM</td>
<td>N/A</td>
<td>N/A</td>
<td>Use to exit back to the Quickware menu.</td>
</tr>
<tr>
<td>DB</td>
<td>RM02/3/5</td>
<td>176700</td>
<td>RP04/5/6</td>
</tr>
<tr>
<td>DK</td>
<td>RK05/03</td>
<td>177400</td>
<td></td>
</tr>
<tr>
<td>DL</td>
<td>RL01/02</td>
<td>174400</td>
<td></td>
</tr>
<tr>
<td>DM</td>
<td>RK06/07</td>
<td>177440</td>
<td></td>
</tr>
<tr>
<td>DP</td>
<td>RP02/03</td>
<td>176700</td>
<td></td>
</tr>
<tr>
<td>DS</td>
<td>RS03/04</td>
<td>172040</td>
<td></td>
</tr>
<tr>
<td>DU</td>
<td>MSCP</td>
<td>172150</td>
<td>MSCP class disk drives such as RA80, RA60...</td>
</tr>
<tr>
<td>DX</td>
<td>RX01</td>
<td>177170</td>
<td></td>
</tr>
<tr>
<td>DY</td>
<td>RX02</td>
<td>177170</td>
<td></td>
</tr>
<tr>
<td>DD</td>
<td>TU58</td>
<td>176500</td>
<td>If SLU 2 is enabled, this may appear to be installed.</td>
</tr>
<tr>
<td>MM</td>
<td>TU16</td>
<td>172440</td>
<td></td>
</tr>
<tr>
<td></td>
<td>TE16</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>TM02/03</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MS</td>
<td>TS04/11</td>
<td>172520</td>
<td>This may appear to be installed due to a conflict with MT tape drives.</td>
</tr>
<tr>
<td>MT</td>
<td>TU10</td>
<td>172522</td>
<td></td>
</tr>
<tr>
<td></td>
<td>TE10/TS03</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MU</td>
<td>TMSCP</td>
<td>174500</td>
<td>TMSCP class tape drives such as TU81, TK50...</td>
</tr>
<tr>
<td>RF</td>
<td>RF11</td>
<td>177460</td>
<td></td>
</tr>
<tr>
<td>FB</td>
<td>use /A:n option</td>
<td></td>
<td>This is provided to boot Foreign Boot rons, such as might be supplied by third party peripheral vendors. These may be booted by specifying their address. e.g. FB/A:171000 or FB/A:175000</td>
</tr>
<tr>
<td>UU</td>
<td>N/A</td>
<td></td>
<td>This is the code for a User-defined boot program. If you select this without first storing a boot program, unpredictable results will occur.</td>
</tr>
</tbody>
</table>

Devices supported by the QED Boot Roms
6.3.6 Boot using M9301/9312

This option of the main menu will allow you to boot a device using a boot program from a 9301 or 9312 boot board, if one is installed. If the boot program for a device is already present in the QED boot roms, (see table above in section 6.3.5) you should consider using that program, rather than the 9312 version, since the QED versions have better error recovery. If you do need to use a boot program installed on a 9301 or 9312, this option will allow you to boot the program on the boot board according to the switches on the boot board. If you wish to boot some other device (other than the one selected by the boot board switches) you can run any program on the boot board by specifying its address with the “FB” pseudo-device. e.g. “FB/A:173204” This command would boot a “foreign-boot” device (i.e. a 9312 board) using 173204 as the starting address.

6.3.7 Halt to ODT

After you select this option, the processor will halt, and ODT will print out a prompt “@”. See chapter eight for more information on using ODT to examine and to deposit to the memory and to the registers. Type a “P” to proceed from ODT back into the menu.

6.3.8 Customize Settings

This option allows you to change the configuration from that selected by the standard defaults above.

6.3.8.1 Configure DL11 Ports

The MS95 has two DL11-compatible serial line units. They are referred to as SLU 1 and SLU 2. The CSR address and vector of SLU 1 is set at the standard console address of 177560/60. SLU 2 is located at the first DL11 address 176500 with a vector of 300. These addresses cannot be changed.

You can set the baud rates for SLU 1 and SLU 2 through this part of the menu. Each SLU can be individually disabled. It is generally unnecessary to change the baud rate for SLU 1, since it is set at boot time by the boot ROMs.

You can halt the QED 95 CPU from the console by pressing the break key. In order for this feature to be used, the console terminal must be connected to SLU 1. This is the standard configuration in the 11/24 and 11/44. To use this feature in other systems such as the 11/34, the existing console DL11 board must be removed and the console terminal must be connected through J3 on the MS95. The 11/24 or 11/44 can also control the Halt-On-Break option by setting the front panel key switch to “Local Disable.” There is no such override in other systems. We recommended that you disable this feature for these other systems. This action prevents accidental halting of
the system while it is on-line. Please note that if you enable Halt on Console Break, the system will halt anytime a break is received from the console terminal, regardless of the setting of the 11/24 or 11/44 front panel. If you disable Halt on Console Break in an 11/24 or 11/44, then the front panel switch on these machines will control this feature. Also, note that when you turn off the console terminal, it may send a break, in which case the system will halt if this option has been enabled.

6.3.8.2 Configure KW11 Clock
The MS95 has a KW11-compatible line clock. This option allows you to disable the on-board KW11 or to set its clock source. This clock should be enabled in 11/24 and 11/44 systems. In most other systems this should be enabled if the system clock has been removed during installation of the QED 95. If the clock is enabled and the system clock is still installed, the system time may advance at double its normal rate. If the clock is enabled, four sources for the clock rate are available. The default and recommended rate is the AC Line. This is used in most systems and will assure that the clock rate is consistent with the original system. The other three sources are from a crystal oscillator. The available rates are 50 Hz, 60 Hz, and 800 Hz.

6.3.8.3 Configure Cache, Processor Registers, and Memory
This sub-menu provides six options, most of which do not usually need to be changed. The first option controls the memory size, but the QED 95 automatically sets the memory size at boot time, so this should not be necessary. The second option is used to enable the Extended Unibus, if you have a 2 MB MS95 installed in an 11/24 or 11/44, and wish to use some of the original EUB memory. (This option is no longer recommended or supported.)

The third option may be used to disable the cache for diagnostic purposes. The cache has three settings - Fully Enabled, Cache Instructions only (No data), or Disabled. For normal operation, the cache should be fully enabled.

The fourth option is used to configure the MS95 for special hardware requirements. If you need to disable extra pages of the Unibus Map, you would use this option. Also, this option can be used to force the MS95 to run only in 18-bit mode, although this would limit the memory size to 256 KB. If you need assistance in using either of these functions, please call our technical support department.

The last two options on this sub-menu are provided to adjust the processor-specific features of the QED 95. Option five, "Configure Switch Register" will allow you to make the switch register nonexistent, read-only, write-only, read and write to the 11/70 front panel, or read and write to an internal register. If you choose to emulate an 11/70, this will already have chosen the 11/70 front panel to be used as the switch register.

The last option, "Configure Quickware special registers", allows you to change many of the special internal registers which are used by the microcode for emulation
variations. You should not need to change any of these registers, except perhaps the System ID register. This register contains the value which can be read at location 177764 in an 11/70 system. On the original PDP-11/70, there was a set of switches which allowed you to change this value, as a type of serial number for each machine. Sometimes, in networked applications, this number is used to uniquely identify each machine. If you need this feature, you can change the System ID register to any value you require. Note that this value is distinct from the value returned by the MFPT (Move from Processor Type) instruction. The microcode for MFPT uses the value in iReg720 to decide what value to return. When the QED 95 is emulating a J-11, this register contains a 5, when emulating an 11/44, it contains a 1, and when emulating an 11/70, it contains a 0, which means that MFPT is not a legal instruction.

6.3.8.4 Select Boot Action
You choose the default boot-time behavior of the QED 95 using this menu selection.

Set Boot to Device Prompt
Selecting this boot action is the same as typing "P" at the main configuration menu prompt. When the QED 95 boots, it will prompt: "Boot device [DDn]?" You can type "?" to see which devices are available. For each supported device, the program attempts to reference the standard CSR for the device. For each device that it finds, the mnemonic is typed in parentheses.

The prompt may also have a default saved with it. This is done after selecting a device at boot time by responding "Y" to the question "Save response for later auto-boot?". If answered "Y," the response to the "Boot Device?" prompt is stored in the EEROM. It is then used as the default for the boot prompt or used in the auto-boot routine described below.

Set Boot to this Menu Program
This option would boot the main configuration menu each time you turn the system on. Generally, you won't want to see the menu each time you boot the machine, so you would choose boot to device prompt or auto boot, rather than this option.

Set Boot to Auto-Boot
You can set the configuration program so that it boots a selected device automatically. To do this, boot the device from the boot device prompt and save the response. Then select "Boot to Auto-Boot" as the boot action. When you reboot the system, the selected device will boot automatically. There is a time-out of about 5 seconds during which you can cancel the auto-boot process with a Ctrl-C. If the desired device is unavailable or does not become ready, the auto-boot procedure will be cancelled.

Set Boot to M9312/M9301
If the system has an M9301 or M9312 bootstrap terminator board installed, the QED 95 can use those ROMs to execute the boot. Since these bootstraps are located at
CHAPTER 6. STARTUP & CONFIGURATION MENU

the same address as the QED 95 boot ROMs, the QED 95 boot ROMs are disabled, and then control is passed to the M9301/12. Location 1773024 on the bootstrap board contains the starting address for these ROMs.

Normally it is unnecessary to use the M9301/12 boot ROMs since most devices are supported by the configuration menu. Use this option only if your boot device is not supported by the QED boot menu.

Set Auto-Baud Time Out

On a cold boot, the boot ROMs check to see if there is a DL11 installed in the system. If so, control is transferred according to the option selected in 6.3.8.4. If there is not a DL11, SLU 1 is enabled and the ROMs begin to wait for a RETURN from the console terminal. The ROMs use the RETURN to synchronize the baud rate. After receiving the RETURN, the configuration menu is loaded and control is transferred according to the option selected in 6.3.8.4. This option allows you to set the amount of time that the ROMs wait for the RETURN. If the time-out elapses, the previous setting for SLU 1 is loaded from the EEROM and the configuration menu appears.

We recommend that you select a time out of 15 seconds.

Set Device Timeout

This option selects how long the Auto-Boot process will wait for a device to become ready before giving up on it. After the specified period of time, an auto-boot is canceled, and the menu prompts for another device to boot.

6.3.8.5 Edit User Defined Boot Programs

If you require a special boot program that is unavailable on an M9301/9312 bootstrap terminator, you may load a program into the EEROM and select it from the boot prompt. You can define up to four user defined boot programs, each 510 bytes long. If you require a longer boot program, you can chain the four programs together. The user boot programs are named UU0 to UU3. They appear as one device mnemonic in the device list. There is no support for multiple devices in one boot program.

To load a new program into a user boot, first retrieve the desired boot program. The program will copy the old EEROM contents into memory from 1000 to 1774 and then halt with the ODT prompt “@.” Using ODT, type the user boot into locations 1000 (8) through 1774 (8). Type “P” to exit ODT. Next select “Store user boot.” You will be prompted for the device to save. If the EEROM save is successful, the program responds with “User Boot Saved.” The user boot program can now be run by exiting back to the main menu and selecting “UUn” at the boot prompt.

Guidelines for writing user boot programs:

1. Write code in position-independent form.
2. Note that, although boot programs are individually edited at locations 1000-1774, all four are loaded into memory from 10000-13776 before they are executed.

3. When selected, the user boot program begins running at 1n000 (8), where n is the UUn unit number. That is, UU0 will be in memory from 10000-10776, UU1 from 11000-11776, etc.

4. Each program will be stored on a separate page in the EEROM at 17765000 (8).

5. The program may not exceed 776 (8) bytes unless it is broken into segments. Please note that location xx776 is reserved for a checksum, and should not be used by the program code. Multi-segment boot programs should branch around this location.

6. To load a segmented boot program, you must store each segment separately in the EEROM.

7. Use the command “RTS PC” to return to the configuration menu.

8. On return to the configuration menu, R5 has the following meaning:
   
   1 = Successful boot of first block.
   270 = Drive not ready.
   271 = Non-bootable media present.
   272 = No disk present.
   273 = No tape present.
   274 = Non-existent controller.
   275 = Non-existent drive.
   276 = Invalid unit #.
   277 = Invalid device
   300 = Controller error.
   301 = Drive error.

   If 1 is returned, the configuration menu will continue with the boot by jumping to location 0 (8). The other errors result in an error message and the boot is retried.

9. If control is returned to the configuration program to continue the boot, R0-R3 will be preserved.

10. Magtape boots generally require R4 point 20 (8) bytes past the ASCII device code. This is to maintain compatibility with M9301/12 boot ROM formats. **R4 is not preserved on a return from the user boot programs.**
Because of this, it is advisable to jump directly to 0 (8) from the user boot program for magtape boots.

11. A checksum is stored with each user boot, in word xxx776. If the EEPROM area containing a user boot becomes corrupted, the self-diagnostics will write a 0 (halt) instruction as the first word of each corrupted user boot. In this way, the machine will halt, rather than executing a damaged boot program.

### 6.4 Revisions

**V2.01**

This was the first version of the boot roms for use with the QED 95.

1. Fixed bug which was clearing PSW in memory clearing routine.
2. Added boots for RK05 (DK), RP03 (DP), RS03 (DS), and RX01 (DX).
3. Increased maximum legal unit number for several devices.

**V2.02**

1. Fixed bug in LTC enable/disable routine.
2. Changed so that maximum memory on MS95 is used by default.
3. Changed some menu options for QED 95 CPU.
4. Added boot for MU (TMSCP tape drives)
5. Changed UU boots, so that they are copied down into memory at 10000 - 13776 before being executed.
7 Operating Systems

The QED 95 addresses 4 MB of memory. To use this amount of memory requires the use of an operating system that can access the extra memory. If your old system had 256 KB of memory (or less), then you will likely want to generate a new operating system in order to use more than 256 KB of memory. (Although you will be able to use the QED 95 with the old system and at least the original amount of available memory.) To generate a new operating system, please refer to the appropriate Digital operating system manual.

If you do generate a new operating system, it is useful to remember that the QED 95 supports both I and D space for memory management. Also, the QED 95 includes Floating Point support (FP-11, or FPP), as well as the Extended Instruction Set (EIS). The QED 95 can include a switch register at 177570, but it does not support the Commercial Instruction Set (CIS) or the EAE or FIS arithmetic options. If your operating system supports directory caching (file processor buffering) or disk caching (data buffering), it may be very helpful to enable these options to use some of the memory to speed up I/O operations.

7.1 RSX

There are no special considerations for RSX.

7.2 RSTS

There are no special considerations for RSTS.
7.3 RT11

There are no special considerations for RT11.

7.4 TSX-Plus

If you sysgen a new TSX-Plus system, you will want to check three important parameters in TGEN. BUSTYP should be set to UNIBUS, EXTMCH to 1, and MEMSIZ to 0. This specifies that you have a Unibus machine, with Extended memory, and that you want to use all the memory that is installed.

7.5 DSM11 (MUMPS)

There are no special considerations for MUMPS.
8 Diagnostics

This chapter describes the software tools that are available to help you diagnose the QED 95 system. First, we describe ODT, which allows you to examine and modify memory and registers. Then, the built-in diagnostics are discussed. Next, some simple diagnostics are presented which can be entered using ODT, allowing you to verify the data paths of the machine. Larger diagnostic programs are discussed next, including those written by Quickware and by Digital. Finally, the last section details some troubleshooting techniques which may be helpful.

8.1 ODT

The QED 95 processor has an ODT (Octal Debugging Tool) built into it. This ODT allows you to examine memory, deposit values into memory, and execute programs.

Commands include:

n/ n may be an octal address, a register specified by R0 thru R17, or RS for the PSW. This will open and display the contents of the specified address, and allow you to enter a replacement value. Carriage Return closes the location, modifying it if you typed a new value, while Line Feed closes (and saves, if necessary) the location and opens the next sequential location. If n is not specified, the last address is used.

Anything with an R or a $ will be treated as a register address. (only the low four bits are significant)

Anything with an S will be treated as a PSW reference.

P Proceed with program execution at the current PC address. This will restore MMR0 from the R10 scratch register. No bus reset will be issued.
CHAPTER 8. DIAGNOSTICS

C Continue with program execution at the current PC address. This will not restore MMR0 from R10, rather, the current contents of MMR0 (777572) will be used for the initial MMR0 contents. No bus reset will be issued.

nG Reset the processor and the Unibus, and begin execution at octal location n. If n is not specified, a default value of 0 is used. Note that MMR0 is cleared, and that a bus Init is part of this sequence.

D Dump the PSW and the eight general registers and eight scratch registers.

Q Force DC LO out onto the bus. This will initialize the bus, reset the system, and restart the boot code.

^S Control-S is ignored.

^Q Control-Q is ignored.

^U Control-U or backspace or delete or any other unknown character will echo a '?' and cancel the input line.

If power fails while the QED 95 is in ODT, an 'F' will print out on the terminal.

If an illegal address is referenced, or any other memory error happens while referencing a memory location, a question mark will print out, and the prompt will be re-displayed.

Addresses and data are always entered and displayed in octal (base 8).

Addresses are always treated as 16 bit values. If you type in more digits, only the lowest 16 bits are used. Thus, 7707123456 is treated as 123456. As a special feature, all addresses are translated using the current state of the MMU. Thus, if the MMU is enabled (bit 0 of MMR0 is on), the PARs selected by the mode in the high bits of the PSW will be used to relocate the address. This may be helpful in debugging, but one must take care that PAR7 of the current mode is always mapped to the I/O page, so that ODT references to the terminal will work.

Note that MMR0 is cleared upon entry to ODT, but a copy of the prior contents is saved away in R10, a scratch register. R10 and MMR0 may be independently modified. R10 will be copied into MMR0 when a Proceed command is issued.

Eight scratch registers may be accessed by using the D command, or by looking at registers R10 through R17. These are associated as follows:

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>R10</td>
<td>The value of MMR0 at the time ODT was entered. (777572)</td>
</tr>
<tr>
<td>R11</td>
<td>The current MMR1 contents. (read-only) (777574)</td>
</tr>
<tr>
<td>R12</td>
<td>The current MMR2 contents. (read-only) (777576)</td>
</tr>
<tr>
<td>R13</td>
<td>MMR3 (772516)</td>
</tr>
<tr>
<td>R14</td>
<td>Memory system error register (77744)</td>
</tr>
</tbody>
</table>
8.2 Built-in Diagnostics

When the QED 95 system is booted, it runs some diagnostics from the built-in boot roms. These tests verify that the processor is operating and can continue the boot process. Next, the QED 95 boot roms test the memory. If the contents of memory are not valid (as would be the case on a cold boot), then the memory is cleared, starting with the highest memory address, and working down to 0. As the memory is cleared, periods print out on the console terminal. After the memory is cleared, the menu program is loaded into memory and run. During a warm boot, when memory does not need to be cleared, the processor still performs some limited tests, and then proceeds with the boot without clearing memory.

If the built-in diagnostics detect an error, the LEDs on the QED 95 CPU will display a code which indicates the test that failed. Refer to Appendix C for a table of the error codes, and the associated tests and likely causes of failure.

8.3 Simple Diagnostics

This section describes some simple tests which you can try by typing them into the QED 95 using ODT. These tests also demonstrate how ODT may be used.

*(computer responses are underlined, your keystrokes are not.)*

<CR> means type a Carriage Return,
<LF> means type a Line Feed,
nnnnnn means any octal number)

8.3.1 Memory Tests

The most basic test of the system is to access the memory. We will try to access location 0, which should contain memory on every system, and then try to access a non-existent memory location. Lastly, we will examine the CPU error register, to see if the CPU can access built-in registers.

With the system in ODT (@ prompt) (enter ODT by pressing the HALT switch, typing a break, or by selecting H in the main menu), try the following:

@0/nnnnnn 0<CR>
If the above test functions correctly, the system is working well enough to try the following tests. If not, check the cables for proper connections.

### 8.3.2 Memory Bus Tests

One very simple test is to try to store several words in the memory and retrieve them, checking that nothing was garbled in between. Again, in ODT, try the following:

```
@/nnnnnn_0<LF>
000002/nnnnnn_1<LF>
000004/nnnnnn_2<LF>
000010/nnnnnn_4<LF>
000012/nnnnnn_20<LF>
000014/nnnnnn_40<LF>
000016/nnnnnn_100<LF>
000020/nnnnnn_200<LF>
000022/nnnnnn_400<LF>
000024/nnnnnn_1000<LF>
000026/nnnnnn_2000<LF>
000030/nnnnnn_4000<LF>
000032/nnnnnn_10000<LF>
000034/nnnnnn_20000<LF>
000038/nnnnnn_40000<LF>
000040/nnnnnn_100000<CR>
```

The first seventeen memory locations are now filled with distinct patterns, each testing a separate data bit. If you examine them, you should see the following:

```
@/000000_0<LF>
000002/000001_1<LF>
000004/000002_2<LF>
000006/000004_3<LF>
000010/000010_4<LF>
000012/000020_5<LF>
```
If you do not get these results, the memory data bus has a problem at some point. If the processor prints out a question mark at any point, it is indicating that it cannot access the memory. Check that the memory is correctly installed. If the numbers printed out are different than the ones you entered, then there is likely a memory data RAM error.

Another simple test is to exercise each of the address lines. In this test, we will write to addresses in memory so that every memory address line is tested. Enter the following, while in ODT:

```
@0/nnnnnn_0<CR>
@2/nnnnnn_1<CR>
@4/nnnnnn_2<CR>
@10/nnnnnn_3<CR>
@20/nnnnnn_4<CR>
@40/nnnnnn_5<CR>
@100/nnnnnn_6<CR>
@200/nnnnnn_7<CR>
@400/nnnnnn_10<CR>
@1000/nnnnnn_11<CR>
@2000/nnnnnn_12<CR>
@4000/nnnnnn_13<CR>
@10000/nnnnnn_14<CR>
@20000/nnnnnn_15<CR>
@40000/nnnnnn_16<CR>
@100000/nnnnnn_17<CR>
```
Now we will verify that the memory has stored our data at the correct addresses.

If there are no errors, the memory system is working, and none of the data or address lines are corrupted. Also, the CPU and the SLU are basically functional.

8.3.3 CPU Tests

To test the CPU, we will first set the registers, examine them, and then run a very short program which will modify the registers.

First, try to set the registers:

\[ \text{Address} / \text{Value} < \text{LF} \]
Now examine them, and verify that they contain the data we wrote:

```
R6/nnnnnn_1000<LF>
R7/nnnnnn_1000<CR>
```

Now, write a simple program to manipulate the registers.

```
@R0/000000<LF>
R1/000001<LF>
R2/000002<LF>
R3/000003<LF>
R4/000004<LF>
R5/000005<LF>
R6/001000<LF>
R7/001000<CR>
```

(Comments are off to the side)

```
@1000/nnnnnn_5005<LF>
001002/nnnnnn_5201<LF>
001004/nnnnnn_10203<LF>
001006/nnnnnn_60302<LF>
001010/nnnnnn_77402<LF>
001012/nnnnnn_20004<LF>
001014/nnnnnn_1401<LF>
001015/nnnnnn_5201<LF>
001020/nnnnnn_0<CR>
```

Execute the program by typing:

```
@1000G
001022
```

@
The program should halt within a second, and print the above response. If it does not, halt the system using the HALT switch. Either the system is not working, or the program was entered incorrectly. If the program does halt, examine the contents of the registers, to see if the program worked correctly.

```
@R0/000000 <LF>
R1/000002 <LF>
R2/000012 <LF>
R3/000002 <LF>
R4/000000 <LF>
R5/000000 <LF>
R6/001000 <LF>
R7/001022 <CR>
```

If there are no mistakes, the CPU, memory, and SLU are functioning.

### 8.3.4 Interrupt Tests

Testing the interrupt system will complete the hand-entered tests of the QED 95 CPU. Various I/O devices interrupt the CPU when they need attention. The device requests the CPU's attention, and when the CPU grants the request for attention, the device responds with a vector at which to find an address to begin execution of a service routine. We will enable the SLU transmitter to interrupt the CPU when it is ready to transmit another character. When the CPU responds, it will send another character to be transmitted. If this works, the CPU is able to respond to interrupts.

Enter the following:

```
@1000/nnnnnn 12737<LF>
001002/nnnnnn 1014<LF>
001004/nnnnnn 177746<LF>
001006/nnnnnn 12737<LF>
001010/nnnnnn 100<LF>
001012/nnnnnn 177564<LF>
001014/nnnnnn 777<CR>
@2000/nnnnnn 12737<LF>
002002/nnnnnn 120<LF>
```
Now execute the program by typing:

`@1000G PPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPPP @`

The program will continue to print the letter P until you press the HALT switch. If no output appears, the processor is not responding to interrupts.

### 8.4 Distributed Diagnostics

Quickware has available a diagnostic package which includes several diagnostic programs written by Quickware to test the QED 95 system, and also includes the Digital XXDP package, distributed under a license agreement.

#### 8.4.1 Quickware Diagnostics

Quickware provides diagnostic programs to test the QED 95 and associated hardware. Programs written specifically for the QED 95 are named `Qttrp.BIC` where `ttt` is the test name, `r` is the revision level, and `p` is the patch level. Also, Quickware distributes some DEC diagnostic programs which have been patched to work with the QED 95. These have a `Q` for the patch level.
Chapter 8. Diagnostics

The following table lists the currently available diagnostics. Consult the file QFILES.TXT on your distribution media for the most current information.

<table>
<thead>
<tr>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>IQCFGDO</td>
<td>Processor identification</td>
</tr>
<tr>
<td>QCP1D0</td>
<td>Processor data bus and instruction tests</td>
</tr>
<tr>
<td>QCP2BD0</td>
<td>Processor data sensitivity test</td>
</tr>
<tr>
<td>QCP3BD0</td>
<td>Extensive Processor instruction test</td>
</tr>
<tr>
<td>QFP1D0</td>
<td>Floating Point test</td>
</tr>
<tr>
<td>QFP2D0</td>
<td>Extensive Floating Point test</td>
</tr>
<tr>
<td>QCA1D0</td>
<td>Cache memory size test</td>
</tr>
<tr>
<td>QCA2D0</td>
<td>Cache memory full test</td>
</tr>
<tr>
<td>QSL1D0</td>
<td>Serial Lines 1 and 2 tests</td>
</tr>
<tr>
<td>QLTCDO</td>
<td>Line Time Clock tests</td>
</tr>
<tr>
<td>QMS910</td>
<td>Memory test</td>
</tr>
</tbody>
</table>

A command file is supplied to automatically run all of the tests. To start it, type the following:

```
.C Q95TST
```

If you want to only run one pass of each test (to quickly verify that everything works) type

```
.C Q95TST/QV
```

The individual tests may be run by typing `R filename` for example:

```
.R QCP1D0
```

All Quickware diagnostics follow a similar format: They will print the program title, and then ask for a new switch register setting. Typing a carriage return will enter the default setting, which is 2000, bell on error. Typing a question mark will list all the values defined for the switch register. These are octal values which may be added together, for example, to select both Halt On Error and Bell On Error, you would enter 102000 followed by a carriage return. The diagnostics will run for ten passes and then
return to the XXDP monitor. If you wish to change the switch register while the diagnostics are running, type a control-G to force the program to prompt for a new switch setting. To stop the diagnostics, type a control-C.

The Quickware-patched DEC diagnostics and QMS910 are designed to be run until the processor is rebooted.

8.4.2 DEC Diagnostics

DEC diagnostics for peripherals should all function normally. These are named Ztttrp.BIC where ttt is the test name, r is the revision level, and p is the patch level. If problems do occur with some diagnostics, it may be the result of the QED 95 CPU's high speed finishing some timing loops faster than expected. We recommend that you disable the cache memory, and try the test a second time. See section 6.3.8.3 for help in disabling the cache. Disabling the cache drastically reduces the CPU speed.

You can build a DECX diagnostic exerciser to test your entire system. The DECX modules are all named Xtttrp.OBJ, and the program DXCL is used to build an exerciser. If you are not familiar with this process, please see the help files QXHELP.TXT and QXHLPI.TXT on the diagnostic medium. Note that the DECX module FPB* which tests the floating point unit will not work properly, due to the asynchronous floating point operation of the QED 95. Modules FPA, CPA, CPB, KWA, BMH, and others work fine.

DEC diagnostics for specific processors or memories will generally not work. Most of these examine processor-specific bits, and will find subtle differences between the DEC processors and the QED 95. The supplied Quickware processor tests should be used to test the processor instead.

8.5 Troubleshooting and Fault Isolation

The following steps will assist you in troubleshooting a QED 95 system. There are two major categories of problems, those which prevent the machine from booting, and those which happen intermittently. Call our technical support department if you are experiencing difficulties.

8.5.1 Hard Failures

Hard failures which occur after the machine has been successfully installed and operating are most likely caused by a single failed component, or by a bad cable. Hard
failures during the initial installation are most likely due to power supply failures, improper installation, static damage, or cables which were not installed properly.

Check list:

1. Turn on the machine, and watch the LEDs
   If they blink or change, go to step 5

2. If all LEDs are off, check that all of the power supplies are providing the correct voltage to the system. Oftentimes a power supply will fail when it is shut down after being in use for a long time. Also check that all the circuit breakers for the system are on.

3. If all LEDs are on, check that the Halt Switch is not on. If it is on, move it to the continue position, and try turning the power off and then back on.

4. If all LEDs are on, check whether each expansion box is powered up. If any expansion box is shut down, DC LO will be asserted, preventing the QED 95 from powering up.

5. Remove the Unibus cable going from the processor box to the expansion boxes. The system should be able to power up part way, even if the expansion boxes are disconnected.

6. Although a far-end bus terminator is essential for good bus characteristics (the MS95 provides bus termination on its end) try removing the terminator to see if this affects the problem. If it does, this normally indicates an open NPG jumper, or the terminator's power supply may be bad.

7. Check all the cables and check the jumpers on each board.

8. If you have a 95-MBA board (in 11/70 systems only), remove it from the backplane. The MBA is only needed for Massbus transfers, and to operate the 11/70 front panel, so you should be able to get to the menu without it.

9. If the LEDs change, look up the value in the table in Appendix C, which will indicate the most likely defective board. If the value does not appear in the table, it normally indicates a CPU error.

10. If the machine halts before displaying a prompt or displaying the menu, check the LEDs. If the system displays the configuration menu, but cannot boot, the problem is most likely in the MS95, or else the grants may not be passing down the bus correctly.

11. If a DMA device blinks repeatedly, but is not able to transfer the boot block, it is quite likely that the DMA device is installed in a slot which is wired to pass NPG grants. Check that the jumper from CA1 to CB1 on that slot of the backplane is removed.
12. If the red or yellow LEDs on the MS95 come on, there might be a memory error. Note that it is normal for these LEDs to blink on during the first few seconds of the self-diagnostics. However, once the memory has begun the clearing process, the LEDs should stay off.

13. If the machine displays the menu, but the normal operating system will not run, try to boot the XXDP diagnostics, and run the Quickware diagnostics.

8.5.2 Intermittent Failures

In order to debug intermittent failures, it is important to develop a log of errors. Each time the system has an intermittent failure, you should make an entry in this log describing the problem as completely as possible. Hopefully, a pattern will develop, indicating that a particular piece of hardware or a particular program exacerbates the problem. If a hardware problem is indicated, run the appropriate diagnostic on that device. Also, build a DECX exerciser which can exercise the suspect device in conjunction with memory accesses and processor operations. Try turning the cache on and off (use the menu option described in 6.3.8.3, or the CON, COFF options in DECX) while running a test, to see if the cache affects the problem. Also, try running the Quickware diagnostics.

If the red or yellow LEDs on the MS95 come on during a failure, it is very likely that there is a DRAM memory chip failure. If the cache memory affects the problem, the cache (which is located on the CPU board) may be implicated. Errors while using the Massbus are most likely to be caused by the MBA board, but may also be caused by missing jumpers or defective circuits on the CPU or AUX boards.
9 Processor Differences

The QED 95 is very similar to the 11/84 and 11/70 processors; however, some differences are inevitable. This section reviews these differences. It may be helpful to software specialists who must determine the exact behavior of the machine.

The QED 95 implements every instruction implemented by the J-11. CIS is not implemented. Software that expects either CIS, or the absence of certain other instructions may fail. However, the majority of software will reconfigure itself at run or compilation time if CIS is not available. The Halt instruction may be configured to Halt, Trap-4, or Trap-10, in Kernel and also in Supervisor or User modes. A configuration register controls this option. A Jump to a register may be configured in the same way as Halt in User mode.

FIS is not implemented; these and all other illegal instructions will Trap through 10. FP-11 instructions are implemented and run asynchronously to the processor (other instructions may execute while the floating point finishes).

The value returned from a move from processor type (MFPT) instruction is controlled by a configuration register. If the register contains 0, a Trap-10 occurs; otherwise, the value will be moved into R0. Thus, MFPT can return any value, except 0.

Reset lasts a minimum of 15 microseconds. It may last longer if no power failure condition is present, and if the MS95 stretches INIT out for the system bus.
You can access the PSW at 777776 or through MTPS, MFPS. The MMU is a complete 22-bit MMU with Kernel, Supervisor and User modes and Instruction and Data spaces.

MMR 0, 1, 2, and 3 are implemented. MMR0 bit 8 (maintenance mode) and bit 12 (MMU trap) are implemented. MMR2 does not track interrupt vectors, as in the 11/45 and 11/70. The PARs are complete, and the PDRs include bit 15, (bypass cache) and a configuration register selects whether PDR bits 0 and 7 are active or read as zero. In this way, 11/70-style PDRs can be emulated.

Programs can run out of the PARs.
CLR, SXT, and MOV perform write-only cycles for the destination operands.
EIS instructions perform read-only cycles for the source operands.
No instructions can be interrupted mid-execution.

Two general register sets are implemented. These are not available at 777700-777717. The console can reference the registers through ODT. Locations 777700-777717 are used for configuration registers to alter the processor behavior slightly. These locations may be set invisible by setting bit 0 of the byte at 777715.

Odd address and time-out errors are detected.

The Stack Limit register is implemented and programmable.
10 Internal Registers

PDP-11 systems use a variety of processor-specific registers. The QED 95 provides a configurable superset of these registers to maximize compatibility with existing software. Several registers may be written during the processor configuration and then set to read-only status. You can make some registers invisible, so that software does not find unexpected registers on what appears to be an older CPU (e.g. System ID register on an 11/44). The following information may help you determine software compatibility. See Appendix A for further details.

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>777776</td>
<td>PSW</td>
<td>Same as J-11</td>
</tr>
<tr>
<td>777774</td>
<td>Stack Limit</td>
<td>As in 11/70; may be set invisible</td>
</tr>
<tr>
<td>777772</td>
<td>PIRQ</td>
<td>Same as J-11</td>
</tr>
<tr>
<td>777770</td>
<td>uPrg Break</td>
<td>R/W or invisible</td>
</tr>
<tr>
<td>777766</td>
<td>CPU Error</td>
<td>Same as J-11</td>
</tr>
<tr>
<td>777764</td>
<td>System ID</td>
<td>May be configured, R/O or invisible</td>
</tr>
<tr>
<td>777762</td>
<td>System Size</td>
<td>&quot; &quot;</td>
</tr>
<tr>
<td>777760</td>
<td>System Size</td>
<td>&quot; &quot;</td>
</tr>
<tr>
<td>777754</td>
<td>Cache Data</td>
<td>R/O; does not track cache as in 11/44</td>
</tr>
<tr>
<td>777752</td>
<td>Hit/Miss</td>
<td>Same as J-11</td>
</tr>
<tr>
<td>777750</td>
<td>Maintenance</td>
<td>May be configured R/W or R/O</td>
</tr>
<tr>
<td>777746</td>
<td>Cache Ctrl</td>
<td>Similar to 11/84</td>
</tr>
</tbody>
</table>
### CHAPTER 10. INTERNAL REGISTERS

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>777744</td>
<td>Memory Error</td>
<td>Similar to 11/84</td>
</tr>
<tr>
<td>777742</td>
<td>High Err Adr</td>
<td>R/O, set by microcode on Trap-114</td>
</tr>
<tr>
<td>777740</td>
<td>Low Err Adr</td>
<td>&quot;</td>
</tr>
<tr>
<td>777734</td>
<td>Mem Config</td>
<td>Bits 5..0 are on MS95, set UB mem size on 11/84</td>
</tr>
<tr>
<td>777732</td>
<td>Diag Data</td>
<td>R/O = 0</td>
</tr>
<tr>
<td>777730</td>
<td>Diag Ctl</td>
<td>R/O = 0</td>
</tr>
<tr>
<td>777700-717</td>
<td>QED 95 configuration registers, may be set invisible.</td>
<td></td>
</tr>
<tr>
<td>7776xx</td>
<td>User PARs and PDRs</td>
<td></td>
</tr>
<tr>
<td>777576</td>
<td>MMR2</td>
<td></td>
</tr>
<tr>
<td>777574</td>
<td>MMR1</td>
<td></td>
</tr>
<tr>
<td>777572</td>
<td>MMR0</td>
<td></td>
</tr>
<tr>
<td>777570</td>
<td>Switch Register</td>
<td>May be set R/W, R/O,W/O, or invisible</td>
</tr>
<tr>
<td>77756x</td>
<td>Console (DL-11) interface</td>
<td>May be disabled</td>
</tr>
<tr>
<td>777546</td>
<td>LTC CSR</td>
<td>May be disabled</td>
</tr>
<tr>
<td>777526</td>
<td>SLU and MS95 configuration register</td>
<td></td>
</tr>
<tr>
<td>777524</td>
<td>Display Register</td>
<td>Similar to 11/84</td>
</tr>
<tr>
<td>777522</td>
<td>Boot Page Control Reg.</td>
<td>Similar to 11/84</td>
</tr>
<tr>
<td>777520</td>
<td>Boot and Diagnostic Reg.</td>
<td>Similar to 11/84</td>
</tr>
<tr>
<td>77650x</td>
<td>Second DL-11 interface.</td>
<td>May be disabled</td>
</tr>
<tr>
<td>773xx</td>
<td>Boot ROM</td>
<td>May be disabled</td>
</tr>
<tr>
<td>772516</td>
<td>MMR3</td>
<td></td>
</tr>
<tr>
<td>7723xx</td>
<td>Kernel PARs and PDRs</td>
<td></td>
</tr>
<tr>
<td>7722xx</td>
<td>Supervisor PARs and PDRs</td>
<td></td>
</tr>
<tr>
<td>772100</td>
<td>Memory CSR</td>
<td></td>
</tr>
<tr>
<td>7702xx-3xx</td>
<td>Unibus Mapping Registers</td>
<td></td>
</tr>
<tr>
<td>765xxx</td>
<td>Boot ROM</td>
<td>May be disabled</td>
</tr>
</tbody>
</table>
11 Technical Details

11.1 Clock Cycles

The clock strategy for the QED 95 is simple and fast. A standard clock cycle consists of two phases, A and B. Phase A lasts 50 ns and is followed by phase B, which also lasts 50 ns. A clock cycle will be stretched into a third phase, C, if the microcode requests a stretched cycle, or if there is a miss on a cache read. Phase C lasts at least 50 ns, or until the memory reference is completed.

Another important timing concept of the QED 95 is known as Cycle-0. Cycle-0 is the first clock cycle of the execution of a new instruction. During Cycle-0, several PALs decode the Instruction Register (IR) and determine the operation class, the registers used, and the proper op-code for the ALU. If the operation can be performed in a single cycle, (such as a register-register Add or Move) then the ALU is cycled, and the microcode remains in the same state for the next instruction. If the operation is a branch, another PAL determines if the branch should be taken. During Cycle-0 of a branch, the ALU is instructed to add the PC and the branch offset. If the branch is taken, the current memory fetch is interrupted (the MMU is presently fetching the next instruction) and the PC is loaded with the new value during Phase C. If the branch is not taken, the ALU does not write the result, and the cycle concludes at the end of Phase B.

11.2 PALs

PALs are used throughout the QED 95 since they allow relatively complex equations to be implemented. They allow us to change the design easily.
11.3 Technology

The technology used in the QED 95 includes high-speed 16-bit processor parts. These parts feature an integrated ALU and a register bank that performs a register-to-register add in 50 ns. PALs are used throughout the design, as they provide flexibility and speed in a compact package. High speed PALs (10 ns) are used in critical sections. Microcode is stored in 25 ns registered RAMs.
11.4 Block Diagram

- ALU
- MMU
- CPU Tags
- Cache Data
- DMA Tags
- Microcode and Control Logic
- FPU Microcode and Control Logic
- Boot Roms
- Massbus Addresses
- Unibus Map
- ECC
- 4 MB DRAM
- Control
- SLUs LTC
- Massbus Control
- Massbus Data
- QMI Bus
- 95-CPU
- 95-AUX
- MS95
- 95-MBA
# 12 Power Consumption

<table>
<thead>
<tr>
<th>BOARD</th>
<th>POWER</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU Board</td>
<td>9.0 Amps.</td>
</tr>
<tr>
<td>95-AUX Board</td>
<td>3.0 Amps.</td>
</tr>
<tr>
<td>95-MBA</td>
<td>1.5 Amps.</td>
</tr>
<tr>
<td>MS95</td>
<td>7.0 Amps.</td>
</tr>
<tr>
<td>UB70</td>
<td>0.1 Amps.</td>
</tr>
<tr>
<td>BB95</td>
<td>2.5 Amps.</td>
</tr>
<tr>
<td>CIM-44</td>
<td>0.5 Amps.</td>
</tr>
<tr>
<td>CIM-60</td>
<td>0.8 Amps.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>SYSTEM</th>
<th>TOTAL POWER</th>
</tr>
</thead>
<tbody>
<tr>
<td>QED 95A</td>
<td>19.0 Amps.</td>
</tr>
<tr>
<td>QED 95B</td>
<td>19.8 Amps.</td>
</tr>
<tr>
<td>QED 95C</td>
<td>19.5 Amps.</td>
</tr>
<tr>
<td>QED 95D</td>
<td>20.6 Amps.</td>
</tr>
</tbody>
</table>
13 Battery Backup

You cannot use the existing battery backup units of the PDP-11/60 or PDP-11/70, since the MS95 will not be located in the memory chassis. Quickware offers an optional battery backup module for both computers. This module supplies emergency power to the DRAMs located on the MS95 memory board during a power failure. The BB95 is a quad board with circuitry to maintain a full charge on a 12 VDC maintenance-free rechargeable battery. During normal operation, the DRAMs receive power directly from the +5 VDC located on both the PDP-11/60 and PDP-11/70 CPU backplanes. When the DC low signal is sensed, power is switched from the DEC backplane to the BB95 board, which supplies the +5 VDC directly to the DRAMs in order to maintain data integrity. A fully-charged battery maintains a 4 MB system for two hours.
14 Environmental Specifications

14.1 Operating Temperature

10°C to 40°C  
(50°F to 104°F)

14.2 Storage Temperature

-40°C to +66°C  
(-40°F to 151°F)

14.3 Humidity

The QED 95 can withstand non-condensing relative humidity up to 95%.

14.4 Altitude

Operating  
Up to 8,000 feet above sea level

Nonoperating  
Up to 30,000 feet above sea level

Vibration  
Withstands normal transportation and installation stress.
15 MTBF

The reliability prediction MTBF (Mean Time Between Failure) was calculated in accordance with Military Standard MIL-HDBK-217E dated 27 October 1986, except the 71502125J and 7174S35P for which the data was supplied by the manufacturer (Integrated Device Technology).

<table>
<thead>
<tr>
<th>Board</th>
<th>Hours</th>
</tr>
</thead>
<tbody>
<tr>
<td>95-CPU</td>
<td>19,324</td>
</tr>
<tr>
<td>95-AUX</td>
<td>47,455</td>
</tr>
<tr>
<td>95-MEM</td>
<td>69,000</td>
</tr>
<tr>
<td>95-MBA</td>
<td>128,358</td>
</tr>
<tr>
<td>UB70</td>
<td>19 Million</td>
</tr>
<tr>
<td>QED 95D System</td>
<td>9,400</td>
</tr>
</tbody>
</table>

Note 1: Revised figures based on a new MIL-HDBK-217F will be published when available. Based on much better performances on all semiconductors, it is anticipated that there will be a positive effect on calculated MTBF.

Note 2: Using the above method on our QED 85 processor upgrade, we calculated its MTBF to be 64,668 hours. However, based on actual returns, the QED 85 has an MTBF of 438,300 hours. Extrapolating data from the QED 85 would indicate the actual MTBF for the QED 95 will be around 63,600 hours.

Note 3: The UB70 board has only one IC.
16 Service

16.1 QED Installation/Service

Quickware offers several levels of service for your QED 95 processor.

1. Every board set is covered by our one-year return-to-factory warranty. The typical turnaround time for the QED 95 is 10 working days.

2. For an annual fee, we offer an extended warranty plan, under which we will deliver replacement boards via overnight delivery.

3. In the U.S.A., both installation and on-site service of the QED 95 are available from Digital Equipment Corporation. Because the QED 95 improves the MTBF and lowers the board count, a reduction in monthly maintenance charges may be realized. To get complete details, either contact your local Digital field service office or Quickware.
Appendix A System Registers

A.1 Notes on System Registers

All unused bits should be assumed to be zero.

The last line indicates which machines implement a register, if it is not universal.

Some registers are cleared on power-up, start (Go), or by the Reset instruction. The
Bus Reset line does not usually effect CPU registers such as these.

Bit values: (octal)

\[
\begin{array}{ccc}
0 &=& 1; \\
1 &=& 2; \\
2 &=& 4; \\
3 &=& 10; \\
4 &=& 20; \\
5 &=& 40; \\
6 &=& 100; \\
7 &=& 200; \\
8 &=& 400; \\
9 &=& 1000; \\
10 &=& 2000; \\
11 &=& 4000; \\
12 &=& 10000; \\
13 &=& 20000; \\
14 &=& 40000; \\
15 &=& 100000
\end{array}
\]
A.2 System Register Descriptions

165000-165776
Boot ROM - EEPROM, or CPU ROM

1702xx-1703xx
Unibus Map Registers
Only the first 31 pairs are used, although all are implemented. Low order bits are stored in the first word of the pair, high order bits in the second word. The 00 location contains low bits; 02 contains high bits. The low-order word contains bits 15-1; bit 0 is always 0. The high order word contains bits 21-16 in bits 5-0. Other bits are always 0.
Only exists on 22 bit Unibus machines. (95, J-11, 44, 70)

172100
Memory Parity Control/Status Register
Resides on memory board. Additional memory boards have CSRs at 172102, 172104, etc. Bit definition varies based on type of memory.
15: Parity error; double bit error on ECC memory
4: Single bit error on ECC memory
1: Disable correction on ECC memory
0: Enable Parity error

1722xx
Supervisor PARs, PDRs
Inst PDRs 00-16
Data PDRs 20-36
Inst PARs 40-56
Data PARs 60-76
Undefined at power-up. Unaffected by Reset or Start.
PARs are 12 bits on 18-bit machines, 16 bits on 22-bit machines.
PAR bit 0 corresponds to Address bit 6.
PDR bits--
15: bypass cache
14-8: Page Length field
7: Attention bit (11/70 only)
6: Page-written
3: Expansion direction 0 = up, 1 = down
2-1 Access control field

- 00 = Non-Res;
- 01 = Read Only;
- 10 = Not used, Abt;
- 11 = Read/write.

11/70 defines 2-0 as ACF, with
- 000 = N/R;
- 010 = R/O;
- 100 = R/W, but trap;
- 110 = R/W;

Typical PAR values are:
0, 200, 400, 600, 1000, 1200, 1400, 177600 (identity map)

Typical PDR values are
77406, 77506 (page ok; but written)

Attention and written bits are cleared when PAR or PDR is written.

1723xx

Kernel PARs, PDRs

- Inst PDRs 00-16
- Data PDRs 20-36
- Inst PARs 40-56
- Data PARs 60-76

See Supervisor PARs/PDRs for bit definitions.

172516

MMR3 - Memory Management Control Register 3

- 5: Enable Unibus Map (on Unibus machines)
- 4: 22 bit enable
- 3: enable CSM instruction
- 2: enable kernel data space
- 1: enable super data space
- 0: enable user data space

Cleared by power-up, start, or reset
95, J-11, 11/44: bits 5-0 R/W
11/70: bit 3 n/a

173000-173776

Boot ROM, EPROM, or 9312 ROMs(4)

17650x

Second (Auxiliary) DL-11/SLU
Standard DL-11-W registers on 85, 90, 95, 24, 44

177520

BtDiag - Boot and Diagnostic Status Register
11/53: Boot and configuration info (Native Register)
APPENDIX A. SYSTEM REGISTERS

11/84: Controls clock select, ROM select, etc.
15: Reboot enable
14: write for byte select for EERom writing
14: read as Power Ok (normally 1)
13: Force Line clock interrupt enable
12: Disable LTC
11-10: LTC clock select:
       00=LTC line; 01=50Hz; 10=60Hz; 11=800Hz.
9: Enable Halt-on-Break
8: Stand-alone mode
7: Disable 173000 ROM
6: Disable 165000 ROM (make invisible)
5: Disable 165000 ROM outputs
4: ROM Write enable (165000)
3: No QMI Memory board present
2-0: Implemented, but no meaning

177522

ROM PCR - Page Control Register for Boot ROMs
15:9 control page of ROM at 173000
6:1 control page of ROM at 165000
90: bits 8,7,0 are always 0. Word only.
95: bits 8,7,0 may be set, but will not affect ROMs. Word only
11/84: bits 15,8,7,0 are not implemented.

177524

CfgDsp-Configuration/Display Register
Has lights for 84, 90, 95
On 84, six bits display, and reads as 8 bit configuration switch
On 90, lower 8 bits display, but all can be r/w. Word only.
On 95, all 16 bits display and are r/w. Word only.

177526

SluCfg, SluCtl - SLU Configuration Register
90, 95: Word only
12: EUB enable
11: 2 MB installed
10: Enable Memory
9: Enable Aux
8: Enable Cons
7: Aux Programmable Baud Rate Disable
6: Cons Prog Baud Rate Disable (default =1)
5-3: Aux Baud Rate
2-0: Cons Baud Rate

**LTCCsr - Line Time Clock(KW-11) Control and Status Register**

- 7: LTC monitor (read only)
- 6: LTC Interrupt Enable
- Other bits 0

**17756x**

**Console DL-11 CSRs**

- **SWR - Switch/Display Register**
  - Has toggle switches/lights on older machines.
  - 90: not implemented
  - 95: may be configured by reg 710 as R/O, W/O, R/W or NXM.
  - 11/44: modified by console program. R/O from program
  - 11/60: cleared on power-up. R/W
  - 11/70: Lights/Switches

**177570**

**MMR0 - Memory Management Control Register 0**

- 15: Non-Resident Abt
- 14: Page Length Abt
- 13: Access Mode Abt
  - (15-13, when set, freeze MMR0[6-1], MMR1, MMR2)
- 12: MMU Trap
- 9: Enable MMU Trap
- 8: Maintenance mode (relocate only dest refs)
- 7: Instruction completed
- 6-5: Mode of abort ref.
- 4: D/I of abort ref. (D = 1)
- 3-1: Page # of abort ref
- 0: Enable MMU

**177574**

**MMR1 - Memory Management Control Register 1**

- 10-8: Second reg. changed
7-3: Amount reg changed, first ref.
2-0: First reg. changed
Read-Only
95, J-11, 11/44, 11/70

177576 MMR2 - Memory Management Control Register 2
Loaded with 16-bit virtual address (PC) at the start of each instruction.
Read-Only
95, J-11, 11/44, 11/60, 11/70

1776xx User PARs, PDRs
Inst PDRs 00-16
Data PDRs 20-36
Inst PARs 40-56
Data PARs 60-76
See Supervisor PARs/PDRs for bit defs.

17770x 95 Scratch Regs.
These four words may be enabled on the 95.

177710 95-CPU Configuration Reg.
On 90 rev C, always writeable, readable when bit 8 is on.
Word writes only.
8: enable reads of this register
5: Disable NXM on writes
4: Force cache miss on data
3: Map data reads through Unibus map.
15-14: CPU rev 00= 90 CPU Rev C
95: Byte writeable
15: r/o VectSeen. Set and used during interrupt vector processing on 95. Not defined at other times.
14-11: 1000 = 95-CPU Rev A-C
7: R/W but no effect
6: Set non-cachable I/O page to 8k/256k
2: Implement Red Stack traps like 11/70
1: Check odd addresses
0: Enable 11/70 style MMU (expanded MMR0, PDR defns)
177712 95 MBA Configuration Reg.
0-2: MBA arbitration priority selection
3: MBA parity polarity
Only low byte may be written

177714 95 Aux Config Reg. 1
0: Enable Stack Limit Register (774)
1: Enable uPrgBrk Register (770)
2: Enable SysID, SysSz Regs. (760, 762, 764)
3: Allow writes to SysID, SysSz, Cache Data
4: Disable Cache Data Reg (754)
5: Disable Maintenance Reg. reads (750)
6: Disable Maintenance Reg. writes (750)
7: Enable Error Address Regs. (740, 742)
8: Enable Diag Regs. (730, 732)
9: Disable Aux Cfg Reg. 2 reads(716)
   Disable Scratch Regs. (70x, 72x, 736, 756)
10: Disable SWR reads (570)
11: Disable SWR writes (570)
12: Disable Boot Regs. (520, 522, 524)
13-15: Switch Register select
Note that 73x and 520 respond from memory board

177716 95 Aux Config Reg. 2
0: Enables reads of 712, 714
7: 4 MB of memory (written to tell MBA logic about NXM limit)
15: ODT

17772x 95 Scratch Regs
These 4 regs may be enabled on the 95.
177720 contains the processor type.
177722 contains an option mask.

177730 Diagnostic Control Register
11/84 uses for diagnostics.
90, 95: always reads as 0.
APPENDIX A. SYSTEM REGISTERS

177732

Diagnostic Data Register
11/84 uses for diagnostics.
90, 95: always reads as 0.

177734

KMCR - Memory Configuration Register
11/84 Implements bits 15-6 for diagnostic purposes.
bit 5 forces 18-bit mode.
bits 4-0 indicate how many extra 8 KB pages should be allocated to the unibus. 0 = default, one 8 KB page
Cleared by DCLO.

177736

95 Scratch Reg.
90: Always reads as 0.
This word may be enabled on the 95.

177740

ErrAdrl - Error Address Low Register
11/70: Contains 16 low bits of address causing parity error
11/60: WCS status register
95: Latches low bits of physical address when MSER bit 15 is set.

177742

ErrAdrH - Error Address High Register
11/70: Bits 5-0 contain high six bits of address causing parity
Error bits 15-14 contain C1,C0 of bus tran type. (00 if read.)
95: Latches high bits of physical address when MSER bit 15 is set.

177744

MSER - Memory System Error Register
15: Cache memory parity error (set by Aborts to 114)
7: High byte parity error
6: Low byte parity error
5: Tag parity error
1: 90 (Rev A & B) force cache miss on data read (0 on 90c)
0: 90 (Rev A & B) map data reads through Unibus Map (0 on 90c).
J-11 - Cleared on Power-up, Start.
90: Word only
95: Word only
11/44 - bits 15, 7-5;
7-5 all set together unless CCR[7] Par Err Abt is set
Cleared by writes, or Start.
11/60 - bits 7-5 only
11/70 - all bits (15-0) implemented. Each bit is cleared by writing a one to it.
11/84 also has bits 14,13.

CCR - Cache Control Register
10: Write wrong parity tag
9: Unconditional cache bypass
8: Flush cache (w/o) (always reads as 0)
7: Parity error abort
6: Write wrong parity data
3: Force miss 1
2: Force miss 0
1: Diagnostic mode: forces NXM word writes to allocate cache. Present on 11/84 and 90 rev A and B; but moved to 710.5 for 90c,95
0: disable cache parity traps
84,85,90,95 - bits 5-4 are 0
90c,95 - Bit 1 is always 0
11/44- Bits13-12, 10-6, 3,2,0
11/60- Bits 7,6,3,2,0 only.
11/70- Bits 5-0 are implemented.
Bits 7,0 vs cache parity errors: 00-miss, update, trap to 114;
01-miss, update, no trap; 1x-miss, abort to 114.

Maint - Maintenance Register
0: Power OK
7-4: Module type

(0010 = 11/84; 0100 = 11/53; 0011 = KXJ11; )
9: Unibus system (valid on J-11 machines)
8: FPJ11 installed. (valid on J-11 machines)
95: All bits r/w, byte accessible
90: Word only
J-11
11/44 has this for cache maintenance.
11/70 has this for cache and memory maintenance.

HMR - Cache Hit/Miss Register
5-0: Cache hit bits. 0 is most recent ref. 1 = hit, 0 = miss.
APPENDIX A. SYSTEM REGISTERS

Read-only
On 11/44, has cache match maintenance features in upper bits.
95, J-11, 11/44, 11/60, 11/70

177754

CDR - Cache Data Register
11/44: contains data loaded into cache from memory.
95: May be configured as r/w
90: Reads contents of 177524 (display reg.).

177756

95 scratch reg
This word may be enabled on the 95.

177760

SysSzL - System Size Register (Low Bits)
11/70 - contains size of memory. Read-only
Low byte is all ones.
High byte indicates number of 8KW blocks -1
(machine with 2048 kb of memory would have 077777
machine with 3840 kb = 177777
4088 kb = 177577)
95 - may be configured as r/w

177762

SysSzH - System Size Register (High bits)
11/70: Read-only. Always 0
95: may be configured as r/w

177764

SysID - System ID Register
11/70 only. Read-only
95: may be configured as r/w

177766

ErrReg - System Error Register
The bits in here record why a Trap-4 occurred.
7: 11/60- Microbreak
7: Illegal halt
6: Odd address
5: Non-existent memory
4: Unibus timeout
3: Yellow stack violation
2: Red Zone stack (any stack vio on 44)
1: 11/60- WCS error
0: 11/60- Illegal internal address
0: 11/44 - Power Failing.
95, 11/70, J-11: only bits 7-2 are implemented. Cleared by writes, power-up, start.
J-11: Cleared by J-11 on power-up, start.
11/44: 7-4, 2, 0 implemented, cleared by writes.
11/60: Only bits 7, 6, 4, 2, 1, 0 implemented. Word only

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>uPrgBrk</td>
<td>microProgram Break Register</td>
</tr>
<tr>
<td>11/60: 12 bits, write only.</td>
<td></td>
</tr>
<tr>
<td>11/70: Lower 8 bits only.</td>
<td></td>
</tr>
<tr>
<td>95 - May be configured as r/w</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PIRQ</td>
<td>Programmed Interrupt Request Reg.</td>
</tr>
<tr>
<td>15-9: Software programmed interrupt request, levels 7-1</td>
<td></td>
</tr>
<tr>
<td>7-5, 3-1: Encoded value of highest PIRQ pending. (Read only)</td>
<td></td>
</tr>
<tr>
<td>Cleared by power-up, Start(Go), Reset.</td>
<td></td>
</tr>
<tr>
<td>95, J-11, 11/44, 11/70</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>StkLim</td>
<td>Stack Limit Register</td>
</tr>
<tr>
<td>15-8 contain lower limit for stack. Cleared on power-up, start (Go), and by Reset.</td>
<td></td>
</tr>
<tr>
<td>A value of 0 places the stack limit at 400.</td>
<td></td>
</tr>
<tr>
<td>95, 11/70, 11/60</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PSW</td>
<td>Program Status Word</td>
</tr>
<tr>
<td>15-14: Current mode</td>
<td></td>
</tr>
<tr>
<td>(00 = kernel, 01 = super, 10 = illegal, 11 = user)</td>
<td></td>
</tr>
<tr>
<td>13-12: Previous mode</td>
<td></td>
</tr>
<tr>
<td>11: Register set</td>
<td></td>
</tr>
<tr>
<td>8: Suspended instruction (CIS)</td>
<td></td>
</tr>
<tr>
<td>7-5: Priority</td>
<td></td>
</tr>
<tr>
<td>4: T-Bit (Trace Traps)</td>
<td></td>
</tr>
<tr>
<td>3-0: Condition Codes NZVC</td>
<td></td>
</tr>
<tr>
<td>95, J-11: 10-8: N/A</td>
<td></td>
</tr>
<tr>
<td>11/44: 11-9: N/A</td>
<td></td>
</tr>
<tr>
<td>11/60: 11-8: N/A, no Super mode</td>
<td></td>
</tr>
<tr>
<td>11/70: 10-8: N/A</td>
<td></td>
</tr>
</tbody>
</table>
Appendix B  Cable Pinouts

B.1 QMI

<table>
<thead>
<tr>
<th></th>
<th>Pin</th>
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# APPENDIX B: CABLE PIN OUTS

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## B.2 Host Adapter

|   | N/C |   | N/C |   | N/C |   | N/C |   | GND |   | HHaltL |   | HDCLO L |   | GND |   | BGN L |   | PwrDwn L |   | InitRes L |   | HHaltL |   | HBR5 L |   | HBR7 L |   | SAM |   | HAdrVal |   | HGrnDone L |   | HAbort L |   | GND |   | DMAReq L |   | GND |   | SrvCtl L |   | HBootEn |   | Tie H |   | GND |
|---|-----|---|-----|---|-----|---|-----|---|-----|---|--------|---|---------|---|-----|---|------|---|----------|---|----------|---|-------|---|-------|---|--------|---|--------|---|--------|---|-------|---|--------|---|--------|---|--------|
| 2 |     |   |     |   |     |   |     |   |     |   |       |   |         |   |     |   |     |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |
| 4 |     |   |     |   |     |   |     |   |     |   |       |   |         |   |     |   |     |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |
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| 8 |     |   |     |   |     |   |     |   |     |   |       |   |         |   |     |   |     |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |
| 10|     |   |     |   |     |   |     |   |     |   |       |   |         |   |     |   |     |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |
| 12|     |   |     |   |     |   |     |   |     |   |       |   |         |   |     |   |     |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |
| 14|     |   |     |   |     |   |     |   |     |   |       |   |         |   |     |   |     |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |
| 16|     |   |     |   |     |   |     |   |     |   |       |   |         |   |     |   |     |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |
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| 32|     |   |     |   |     |   |     |   |     |   |       |   |         |   |     |   |     |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |
| 34|     |   |     |   |     |   |     |   |     |   |       |   |         |   |     |   |     |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |   |       |   |           |   |           |   |       |
### B.3 CIM Connector

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Appendix C  LED Definitions

C.1 MS95 LEDs

The MS95 memory board has three LEDs which are defined as follows:

Green    Power is present in the memory array.
Yellow   A single bit error has occurred.
Red      A double bit error has occurred.

C.2 QED 95 AUX LEDs

The QED 95 AUX has sixteen red LEDs on it. (Four groups of four.) These LEDs are addressed by the Boot Display Register at 177524. The Boot Roms write to these LEDs as the internal diagnostics are run. If the internal diagnostics detect an error, the value displayed by the LEDs will indicate what type of error was found. Use the following table to find the error, given an LED value. The value displayed by the LEDs is an octal number, with a lit LED indicating a one, and an off LED indicating a zero.

If the QED 95 is installed in an 11/70 system, the front panel Data LEDs will display the inverted version of the value written to the AUX LEDs. By reading the octal value from the front panel Data LEDs (treating a lit LED as a zero, and an off LED as a one) you can easily see the value displayed by the diagnostic LEDs. Note that these front panel LEDs are also written to when the Display Register (at 177570) is written. Thus, once a diagnostic program or operating system writes to this address, the Boot Diagnostic code will be overwritten on the front panel.
If all LEDs are off, the QED 95 is not receiving proper power. Check the system power supplies, review the installation, and make sure that the proper jumpers are installed, and that the boards are in the correct slots.

If all LEDs are on, the QED 95 system has not powered up properly. DCLO may be on, check all cables, and review the installation.

If some LEDs are on, use the following chart to determine the source of the error.

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<th>Meaning</th>
<th>Source of trouble</th>
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<td>Rom Page Ctrl Register not initialized</td>
<td>AUX, CPU</td>
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<tr>
<td>2</td>
<td>Boot and Diagnostic Register wrong</td>
<td>AUX, CPU</td>
</tr>
<tr>
<td>3</td>
<td>Memory System Error Register wrong</td>
<td>CPU</td>
</tr>
<tr>
<td>4</td>
<td>Cache Control Register wrong</td>
<td>CPU</td>
</tr>
<tr>
<td>5</td>
<td>Maintenance Register wrong</td>
<td>AUX, CPU</td>
</tr>
<tr>
<td>6</td>
<td>CPU failed register tests</td>
<td>CPU</td>
</tr>
<tr>
<td>7</td>
<td>Checksum on Boot Rom page 0 failed</td>
<td>AUX, Boot ROM</td>
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<tr>
<td>10</td>
<td>Rom Page Ctrl Register failed</td>
<td>AUX</td>
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<td>11</td>
<td>EEROM missing subroutines</td>
<td>AUX, EEROM</td>
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<td>Checksum on Boot Rom failed</td>
<td>Boot ROM, AUX</td>
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<td>couldn't jump off of boot page 0</td>
<td>AUX, Boot Rom, Page Ctrl Register</td>
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<td>14</td>
<td>Burning EEROM</td>
<td>AUX, EEROM</td>
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<td>15</td>
<td>Stack Pointer is bad</td>
<td>CPU</td>
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<td>16</td>
<td>MMU PARs are bad</td>
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<tr>
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<td>MMU PARs are bad</td>
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<td>MMU PARs are bad</td>
<td>CPU</td>
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<td>21</td>
<td>Subroutine Call failed</td>
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<td>22</td>
<td>CPU type not determined</td>
<td>CPU</td>
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<td>CPU not a QED 90 or 95</td>
<td>CPU</td>
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<td>QED 90 CPU test failed</td>
<td>CPU</td>
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<td>25</td>
<td>QED 90 CPU test failed (rev A or B)</td>
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<td>26</td>
<td>Maintenance Register failed</td>
<td>AUX, CPU</td>
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<td>27</td>
<td>Memory System Error Register failed</td>
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<tr>
<td>30</td>
<td>Cache Control Register failed</td>
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<td>31</td>
<td>Boot Diagnostic Register failed</td>
<td>AUX, CPU</td>
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<td>ROM Page Control Register failed</td>
<td>AUX</td>
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<td>Jump to boot page 14 failed</td>
<td>AUX, Boot ROMs, Page Ctrl Reg.</td>
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<td>QED 90 CPU test failed (Rev C or later) Maintenance Register</td>
<td>CPU</td>
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<td>37</td>
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<td>AUX, CPU</td>
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</table>
40 ROM Page Control Register failed
41 Jump to boot page 14 failed
42 QED 95 CPU test failed, Maintenance or Config Register
43 Memory System Error Register failed
44 Cache Control Register failed
45 Boot Diagnostic Register failed
46 ROM Page Control Register failed
47 Jump to next boot page failed
48 AUX RAM-based register failed
49 Stack Limit Register failed
50 Jump to boot page 14 failed
51 (Boot Page 14) EERom failed -- version
52 EERom failed -- checksum
53 EERom failed -- user pages
54 (Boot Page 16) Config/Display LEDs failed
55 Hit/Miss Register failed
56 Subroutine Call through EERom failed
57 No Memory installed
58 SLU/Cfg Register failed (first memory board access)
59 Write to Memory CSR failed
60 Cache Control Register failed
61 Quick memory scan failed
62 Read of Memory CSR failed
63 Jump to Cold Boot failed
64 Warm Boot failed
65 Parameter recall/setting failed
66 Restarting via (24)
67 Booting through menu/prompt
### APPENDIX C. LED DEFINITIONS

<table>
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<tr>
<th>LED</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AUX</td>
<td>Jump to boot failed</td>
</tr>
<tr>
<td>CPU</td>
<td>(Cold Boot) Stand-alone mode failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Cache failed to record a Hit</td>
</tr>
<tr>
<td>CPU</td>
<td>Cache failed to hold correct data -- 0</td>
</tr>
<tr>
<td>CPU</td>
<td>Cache failed to hold correct data -- 177777</td>
</tr>
<tr>
<td>CPU</td>
<td>Cache data store failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Cache data retrieval failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Cache patterns failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Cache address lines failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Cache size failed</td>
</tr>
<tr>
<td>AUX</td>
<td>Write to cache or jump boot page failed</td>
</tr>
<tr>
<td>CPU</td>
<td>MMU enable failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Writes to cache through MMU failed</td>
</tr>
<tr>
<td>AUX</td>
<td>Cache Tags failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Cache failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Subroutine in Cache failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Subroutine in Cache failed</td>
</tr>
<tr>
<td>AUX</td>
<td>CCR failed or FP or jump boot page failed</td>
</tr>
<tr>
<td>AUX</td>
<td>Floating Point Status failed -- 0</td>
</tr>
<tr>
<td>AUX</td>
<td>Floating Point Status failed -- 147757</td>
</tr>
<tr>
<td>AUX</td>
<td>Floating Point Registers failed -- 0</td>
</tr>
<tr>
<td>AUX</td>
<td>Floating Point Registers failed -- 177777</td>
</tr>
<tr>
<td>AUX</td>
<td>Floating Point math error</td>
</tr>
<tr>
<td>AUX</td>
<td>Floating Point error</td>
</tr>
<tr>
<td>AUX</td>
<td>Jump to next boot page failed</td>
</tr>
<tr>
<td>CPU</td>
<td>Memory failed</td>
</tr>
<tr>
<td>Memory</td>
<td>Low Memory could not be cleared</td>
</tr>
<tr>
<td>Memory</td>
<td>Memory clear routine could not be transferred</td>
</tr>
<tr>
<td>Memory</td>
<td>Clearing memory</td>
</tr>
<tr>
<td>Memory</td>
<td>Setting Parameters</td>
</tr>
<tr>
<td>Memory</td>
<td>Setting Baud Rate of terminal</td>
</tr>
<tr>
<td>Memory</td>
<td>Booting</td>
</tr>
<tr>
<td>EEROM</td>
<td>Boot ROM boot selection invalid</td>
</tr>
<tr>
<td>Memory</td>
<td>Failure while checking SLU</td>
</tr>
<tr>
<td>Memory</td>
<td>Failure while enabling on-board SLU</td>
</tr>
<tr>
<td>Memory</td>
<td>Waiting for Carriage Return to Auto-Baud</td>
</tr>
<tr>
<td>Memory</td>
<td>Failure while checking LTC</td>
</tr>
<tr>
<td>Memory</td>
<td>Line Time Clock failed</td>
</tr>
</tbody>
</table>
154  Waiting for Carriage Return to Auto-Baud
155  Checking speed of received character
156  Waiting for Carriage Return to Auto-Baud